

Learning Objectives



Goal/algorithm



Quantity/object



Property of solution

① Using the complex inner product to define **Gram-Schmidt****Orthonormalization for complex vectors**Input: **set of vectors** in a specific orderoutput: **set of vectors** that **span the same subspace** as our input set, but is also **orthonormal**② **Complex projections**③ Using the complex inner product to define **Least Squares solution and least squares projection for complex vectors**"Input": **A, \vec{x}, \vec{b}** (Solve **$A\vec{x} \approx \vec{b}$**) A - complex matrix of knowns \vec{b} - complex matrix of known measurements \vec{x} - unknown variables in vector, complex valuedOutput: **$\hat{\vec{x}}$** - Least Squares solution **$\hat{\vec{b}} = \text{proj}_{\text{col}(A)} \vec{b}$** - Least squares projection (projection of \vec{b} onto column-space of A)Where $\hat{\vec{x}}$ and $\hat{\vec{b}}$ satisfy

$$\min_{\vec{x}} \|A\vec{x} - \vec{b}\|^2 = \|A\hat{\vec{x}} - \vec{b}\|^2 = \|\hat{\vec{b}} - \vec{b}\|^2 \quad \leftarrow$$

"The smallest value of the length of error $A\vec{x} - \vec{b}$ is" achieved by $\hat{\vec{x}}$

④ General Questions on complex inner products

Mnemonic: $\langle \vec{a}, \vec{b} \rangle = \vec{b}^* \vec{a}$ (reverse order)
for convention

OR

$$\langle \vec{a}, \vec{b} \rangle = \vec{a}^T (\vec{b}^*) \quad (\text{conjugate the second argument})$$

Equal because:

$$\vec{b}^* \vec{a} = \underline{(\vec{b}^*)^T} \vec{a} = \underline{\vec{a}^T (\vec{b}^*)}$$

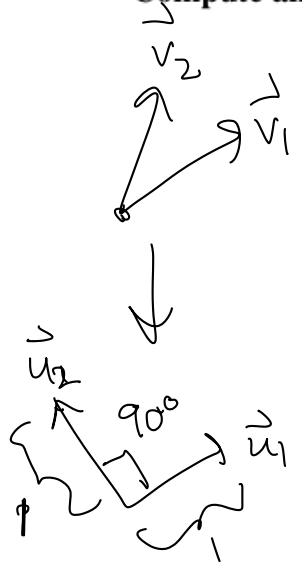
$$\vec{a}^T (\vec{b}^*) = \sum_{i=1}^n a_i \bar{b}_i$$

1. Gram Schmidt on Complex Vectors

(a) Consider the three complex vectors

$$\vec{v}_1 = \begin{bmatrix} 1 \\ j \\ 0 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} \quad \vec{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Compute an orthonormal basis from this list of vectors with Gram Schmidt.



① Normalize $\vec{v}_1 \rightarrow \vec{u}_1$

$$\vec{u}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|} = \frac{\vec{v}_1}{\sqrt{\langle \vec{v}_1, \vec{v}_1 \rangle}}$$

norm relies on new complex inner product

$$\langle \vec{v}_1, \vec{v}_1 \rangle = \vec{v}_1^* \vec{v}_1 = \begin{bmatrix} 1 \\ j \\ 0 \end{bmatrix}^T \begin{bmatrix} 1 \\ j \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -j \\ 0 \end{bmatrix}^T \begin{bmatrix} 1 \\ j \\ 0 \end{bmatrix} = 1 + 1 = 2$$

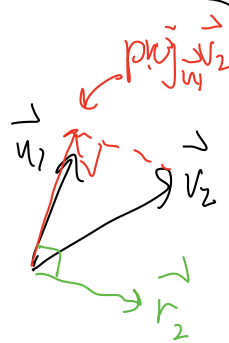
$$\vec{u}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ j \\ 0 \end{bmatrix}$$

② Project onto current set of orthonormal vectors and remove to get orthogonal vector.

$$\vec{r}_2 = \vec{v}_2 - \text{proj}_{\vec{u}_1} \vec{v}_2 = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} - \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{j}{\sqrt{2}} \\ 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{-j}{\sqrt{2}} & 0 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix}$$

$$\text{proj}_{\vec{u}_1} \vec{v}_2 = \frac{(\vec{u}_1)^* \vec{v}_2}{\vec{u}_1^* \vec{u}_1} \vec{u}_1 = \frac{\langle \vec{v}_2, \vec{u}_1 \rangle}{\langle \vec{u}_1, \vec{u}_1 \rangle} \vec{u}_1$$

points along \vec{u}_1



Q: Why \vec{r}_2 ? A: So that \vec{r}_2 is $\perp \vec{u}_1$

$$\langle \vec{v}_2 - \frac{\langle \vec{v}_2, \vec{u}_1 \rangle}{\langle \vec{u}_1, \vec{u}_1 \rangle} \vec{u}_1, \vec{u}_1 \rangle = \vec{u}_1^* \left(\vec{v}_2 - \frac{\langle \vec{v}_2, \vec{u}_1 \rangle}{\langle \vec{u}_1, \vec{u}_1 \rangle} \vec{u}_1 \right) = 0$$

$$\begin{aligned} \vec{r}_2 &= \vec{v}_2 - \text{proj}_{\vec{u}_1} \vec{v}_2 = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} - \underbrace{\begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{bmatrix}}_1 \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} - \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \underbrace{\begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{bmatrix}}_{\text{projection matrix onto } \vec{u}_1} \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} - \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \left(\frac{1}{\sqrt{2}} + 0 + 0 \right) \end{aligned}$$

$$\vec{r}_2 = \begin{bmatrix} 0 \\ -1 \\ 0 \end{bmatrix} - \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}$$

$$\vec{u}_2 = \frac{\vec{r}_2}{\|\vec{r}_2\|} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \left\{ \vec{u}_1, \vec{u}_2 \right\} = \left\{ \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \right\}$$

③ Repeat step 2: remove from new vector (\vec{v}_3) projections onto current orthonormal set ($\{\vec{u}_1, \vec{u}_2\}$)

$$\vec{r}_3 = \vec{v}_3 - \text{proj}_{\vec{u}_1} \vec{v}_3 - \text{proj}_{\vec{u}_2} \vec{v}_3 \quad \left(\vec{r}_3 \text{ is orthogonal to } \vec{u}_1, \vec{u}_2 \right)$$

$$\vec{u}_3 = \frac{\vec{r}_3}{\|\vec{r}_3\|} \quad \vec{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\vec{u}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \|\vec{u}_3\| = 1$$

(b) **Derive the least-squares solution for the case of a complex tall matrix of data and a tall matrix of values.** We want to find the best (complex) linear combination of the columns for predicting the observed values in a least-squares sense — we want to minimize the norm of the residual.

This can be formulated as having a feature matrix of data $D \in \mathbb{C}^{m \times n}$ where $m > n$ and measurements $\vec{y} \in \mathbb{C}^m$. In this case, feel free to assume that the columns of D are linearly independent even when we allow complex linear combinations. **First assume that the columns of D are orthonormal.** Hint: You may find it useful to define a matrix $U = [D \quad D_\perp]$, obtained via Gram-Schmidt. Recall that the procedure here resembles that used in the SVD derivation (one portion of U contains the data/info we “care about”, and the remainder is there via extension, to span the space.)

Strategy: would like to separate quantity of interest into part we can minimize/control and error that will always exist.

$$D = \begin{bmatrix} D_{11} & D_{12} & \dots & D_{1n} \\ D_{21} & D_{22} & \dots & D_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ D_{m1} & \dots & \dots & D_{mn} \end{bmatrix}$$

(D is tall)

$\rightarrow D_{ij} \in \mathbb{C}$
(entries are complex #'s)

$D \vec{x} \approx \vec{y}$ has complex #'s
has complex #'s
How to find \vec{x} w/ complex values such that a solution

Real case:

D has orthonormal cols: $D^T D = I$

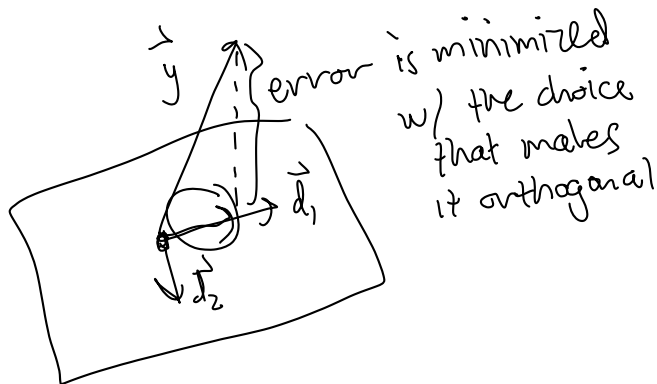
\vec{x} makes $\| \underbrace{D \vec{x} - \vec{y}}_{\text{error}} \|^2$ as small as possible

Complex case:

D has orthonormal cols: $D^* D = I$ ← take inner products of cols of D complex

$$D^* D = \begin{bmatrix} \vec{d}_1^* \\ \vdots \\ \vec{d}_n^* \end{bmatrix} \begin{bmatrix} \vec{d}_1 & \dots & \vec{d}_n \\ \vdots & & \vdots \end{bmatrix} \rightarrow \vec{d}_i^* \vec{d}_j = \langle \vec{d}_j, \vec{d}_i \rangle$$

$\rightarrow U^* U = I$ $U U^* = I$ ($DD^* \neq I$ because D is not a full basis for \mathbb{C}^m)



$$\min_{\vec{x}} \| D\vec{x} - \vec{y} \|^2$$

$$U = \left[D \mid D_+ \right]$$

$$\| D\vec{x} - \vec{y} \|^2 = \langle D\vec{x} - \vec{y}, D\vec{x} - \vec{y} \rangle$$

$$UU^* = U^*U = I \leftarrow$$

$$(AB)^* = B^*A^*$$

$$\| U(D\vec{x} - \vec{y}) \|^2 = \langle U\vec{e}, U\vec{e} \rangle$$

$$= (U\vec{e})^* U\vec{e}$$

$$= \vec{e}^* U^* U\vec{e}$$

$$= \vec{e}^* \vec{e}$$

Orthonormal matrix
U doesn't change norm

$$= \langle \vec{e}, \vec{e} \rangle = \|\vec{e}\|^2 = \| D\vec{x} - \vec{y} \|^2$$

Q: Why \rightarrow U, U* keep length the same

$$\| U^* (D\vec{x} - \vec{y}) \|^2 = \left\| \begin{bmatrix} D \\ D_+ \end{bmatrix} (D\vec{x} - \vec{y}) \right\|^2 \quad \text{Assumed}$$

$$= \left\| \begin{bmatrix} D^* D\vec{x} \\ D_+^* D\vec{x} \end{bmatrix} - \begin{bmatrix} D^* \vec{y} \\ D_+^* \vec{y} \end{bmatrix} \right\|^2$$

$$D^* D = I$$

$D_+ \rightarrow$ comes from GS w/ D

$D_+^* D = 0$ (matrix)
 \rightarrow helps span \mathbb{C}^m

$$\begin{pmatrix} 2 \\ 1 \end{pmatrix} = 2^2 + 1^2$$

$$\begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} = \left\| \begin{pmatrix} 2 \\ 2 \end{pmatrix} \right\|^2 + 1^2$$

$$= \left\| \begin{bmatrix} \vec{x} \\ 0 \end{bmatrix} - \begin{bmatrix} D^* \vec{y} \\ D_+^* \vec{y} \end{bmatrix} \right\|^2$$

$$= \left\| \begin{bmatrix} \vec{x} - D^* \vec{y} \\ -D_+^* \vec{y} \end{bmatrix} \right\|^2$$

top n entries affected by \vec{x}
bottom m-n entries are not affected by \vec{x}

$$= \underbrace{\| \vec{x} - D^* \vec{y} \|^2 + \| -D_+^* \vec{y} \|^2}_{\text{Choose } \vec{x} = D^* \vec{y} \text{ to make above quantity as small as possible}}$$

\Rightarrow Choose $\vec{x} = D^* \vec{y}$ to make above quantity as small as possible

$$\vec{x} = D^* \vec{y} \leftarrow D \text{ was orthonormal}$$

(least squares solution)

$$\vec{x} = (D^T D)^{-1} D^T \vec{y} \quad \text{real case}$$

(c) Repeat the previous part without the assumption of orthonormality for the columns of D . You can keep the assumption of linear independence.

This is a different approach than in the solutions. Read both!

GS makes D_+ from D

$$D = \begin{bmatrix} | & & | \\ d_1 & \dots & d_n \\ | & & | \end{bmatrix}$$

GS on $\left\{ \begin{matrix} \vec{d}_1, \dots, \vec{d}_n, \vec{e}_1, \dots, \vec{e}_m \\ \rightarrow [D \ D_+] \end{matrix} \right\}$

$\vec{e}_i =$ vector w/ i -th entry 1

$$GS [D | I] \rightarrow \begin{matrix} m \times m \\ [Q | D_+] \\ \uparrow \end{matrix}$$

$$D = QR$$

Q has the same column span as D but has orthonormal columns
 $Q^* Q = I$

$$\min_{\vec{x}} \| D\vec{x} - \vec{y} \|^2$$

$$\| QR\vec{x} - \vec{y} \|^2$$

R is a matrix that encodes (complex) linear combinations used in GS

$$= \left\| \begin{bmatrix} Q^* \\ D_+^* \end{bmatrix} (QR\vec{x} - \vec{y}) \right\|^2$$

$$= \left\| \begin{bmatrix} R\vec{x} \\ \vec{0} \end{bmatrix} - \begin{bmatrix} Q^* \vec{y} \\ D_+^* \vec{y} \end{bmatrix} \right\|^2$$

$$= \| R\vec{x} - Q^* \vec{y} \|^2 + \| -D_+^* \vec{y} \|^2$$

minimize by choosing $R\vec{x} = Q^* \vec{y}$

$$\vec{x} = R^{-1} Q^* \vec{y}$$

How to get this?

Check if $(D^* D)^{-1} D^*$ gives

$$(D^* D)^{-1} D^* = ((QR)^* QR)^{-1} (QR)^*$$

$$= (R^* \cancel{Q^*} \overset{I}{Q} R)^{-1} R^* Q^*$$

$$= (R^* R)^{-1} R^* Q^*$$

$$= R^{-1} (R^*)^{-1} R^* Q^*$$

$$= R^{-1} Q^* \checkmark$$

So:

(when D has non orthonormal columns)

$$\vec{x} = (D^* D)^{-1} D^* \vec{y}$$

Questions from 14A, 14B

2. Q&A time! [≈ 20 minutes]

This time is here for you all to ask any questions from discussion 14A and 14B to the TAs to review the material on complex vectors. If there are no further questions, then feel free to discuss anything else related to the course content, as this is the last non-review discussion.

Q: Why is $U^* = \begin{bmatrix} D^* \\ D_+^* \end{bmatrix}$ $U = \left[\begin{array}{c|c} \begin{matrix} \vec{1} & \vec{1} & \dots & \vec{1} \\ d_1 & d_2 & \dots & d_n \end{matrix} & \begin{matrix} \vec{1} & \vec{1} \\ d_{n+1} & \dots & d_m \end{matrix} \end{array} \right]$

$U^* = \begin{bmatrix} -\vec{d}_1^T \\ -\vec{d}_2^T \\ \vdots \\ -\vec{d}_m^T \end{bmatrix} = \begin{bmatrix} D^* & \leftarrow n \times m \\ D_+^* & \leftarrow (m-n) \times m \end{bmatrix}$

↑
transpose + conjugate

Q: Is $UU^* = I$ if U is orthonormal in the complex case? and square

U^*U vs. UU^*

$\begin{bmatrix} \langle \vec{u}_1, \vec{u}_1 \rangle & \dots & \langle \vec{u}_m, \vec{u}_1 \rangle \\ \vdots & & \vdots \\ \langle \vec{u}_1, \vec{u}_m \rangle & \dots & \langle \vec{u}_m, \vec{u}_m \rangle \end{bmatrix}$

A:

$U^*U = I$

$UU^*U = U \cdot I$

$(UU^*)U = U$

$\underbrace{(UU^*)}_I U = U$ has to be true

Q: If U orthonormal and tall is $UU^* = I$ and is $U^*U = I$?

A: From real matrices know for sure that $UU^* \neq I$

$\square \rightarrow$ boils down to UU^T when real

$U^*U = I \checkmark$

$UU^* \neq I$ when U tall orthonormal

When rows of wide U are orthonormal, $UU^* = I$ $U^*U \neq I$

Q: When is upper triangularization the same as SVD? (real matrices)

A: My guess: when A , a matrix is symmetric ($A = A^T$)

$A = V \Lambda V^T \Leftrightarrow$ upper triangularization for symmetric A is its diagonalization
(not true)

SVD: $A^T A = V \Lambda^2 V^T \Rightarrow \sigma_i = \sqrt{\lambda_i} = |\lambda_i|$
left singular vectors being \vec{v}_i

$$U = \begin{bmatrix} \text{sign}(\lambda_1) \vec{v}_1 & \dots & \text{sign}(\lambda_n) \vec{v}_n \\ \vdots & & \vdots \end{bmatrix}$$

Guess
Maybe a chance when $A = A^T$ and A has non-negative eigenvalues

Q: $\langle \vec{a}, \vec{b} \rangle \stackrel{?}{=} \langle \vec{b}, \vec{a} \rangle$

$$\vec{a} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}, \vec{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

$$A: \langle \vec{a}, \vec{b} \rangle = \vec{b}^* \vec{a} = \sum_{i=1}^n a_i \bar{b}_i$$

$$\langle \vec{b}, \vec{a} \rangle = \vec{a}^* \vec{b} = \sum_{i=1}^n \bar{a}_i b_i$$

$$\overline{\langle \vec{a}, \vec{b} \rangle} = \overline{\left(\sum_{i=1}^n a_i \bar{b}_i \right)} = \sum_{i=1}^n \overline{a_i \bar{b}_i} = \sum_{i=1}^n \bar{a}_i \overline{\bar{b}_i} = \sum_{i=1}^n \bar{a}_i b_i = \langle \vec{b}, \vec{a} \rangle$$

Q: When to use triangularization vs. SVD?

A: Upper triangularization \rightarrow wanted to consider DE with a matrix that wasn't diagonalizable (still want benefit of simpler nested problems)

SVD \rightarrow Minimum energy control / understanding subspaces of matrix A and possible solutions to $A \vec{x} = \vec{y}$