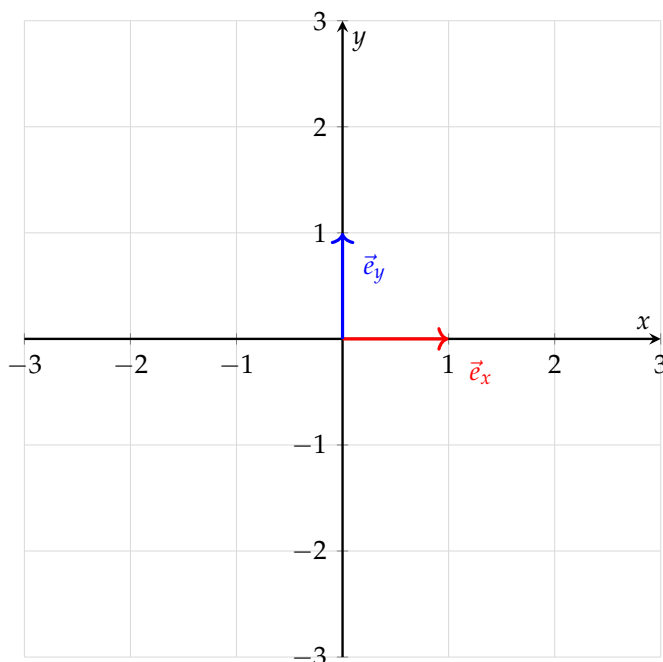


The following notes are useful for this discussion: [Note 16](#)

### 1. Geometric Interpretation of the SVD

- (a) When we plot the transformation given by a specific matrix, we think about how the matrix transforms the standard basis vectors. In 2D, let  $\vec{e}_x = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$  and  $\vec{e}_y = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . The vectors  $\vec{e}_x$  and  $\vec{e}_y$  are shown below

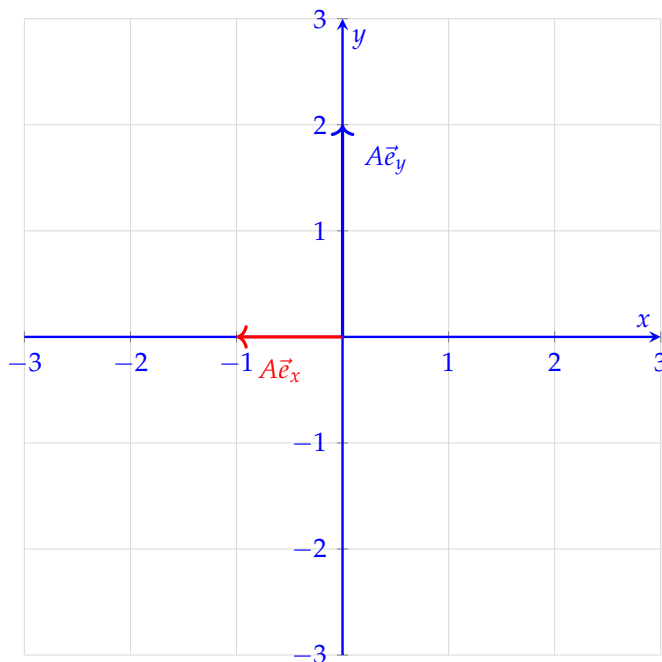


Consider the following matrix

$$A = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \tag{1}$$

**How would  $A$  transform  $\vec{e}_x$  and  $\vec{e}_y$ ? Plot the result.**

**Solution:** We have that  $A\vec{e}_x = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$  and  $A\vec{e}_y = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$ . Plotting these, we have



(b) Let's take a look at a special  $2 \times 2$  matrix.

$$R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \quad (2)$$

**Show that this matrix is orthonormal.** This matrix is called a rotation matrix and will rotate any vector counterclockwise by  $\theta$  degrees.

**Solution:** We can also show orthonormality by showing that the columns have unit norm and that they are orthogonal. We can also show that this matrix is orthonormal by showing that  $RR^T = I_{2 \times 2}$  and  $R^T R = I_{2 \times 2}$ .

$$\|\vec{r}_1\| = \left\| \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} \right\| = \sqrt{\cos^2 \theta + \sin^2 \theta} = 1 \quad (3)$$

$$\|\vec{r}_2\| = \left\| \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix} \right\| = \sqrt{\sin^2 \theta + \cos^2 \theta} = 1 \quad (4)$$

$$\langle \vec{r}_1, \vec{r}_2 \rangle = \begin{bmatrix} -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} = -\cos \theta \sin \theta + \cos \theta \sin \theta = 0 \quad (5)$$

(c) Now let's consider how this transformation looks in the lens of the SVD. You are given the following matrix  $A$ :

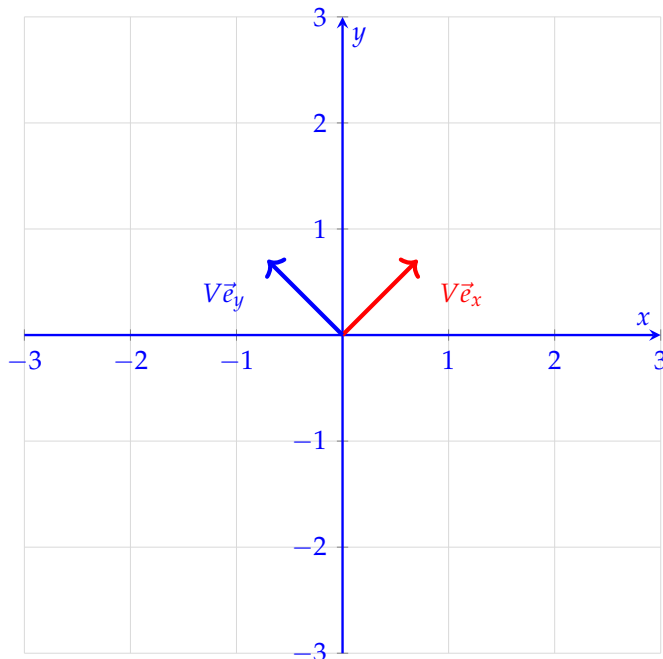
$$A = \begin{bmatrix} -1 & -2 \\ 2 & 1 \end{bmatrix} \quad (6)$$

Recall that the SVD of this matrix is given by  $A = U\Sigma V^T$ . Assume you are told that

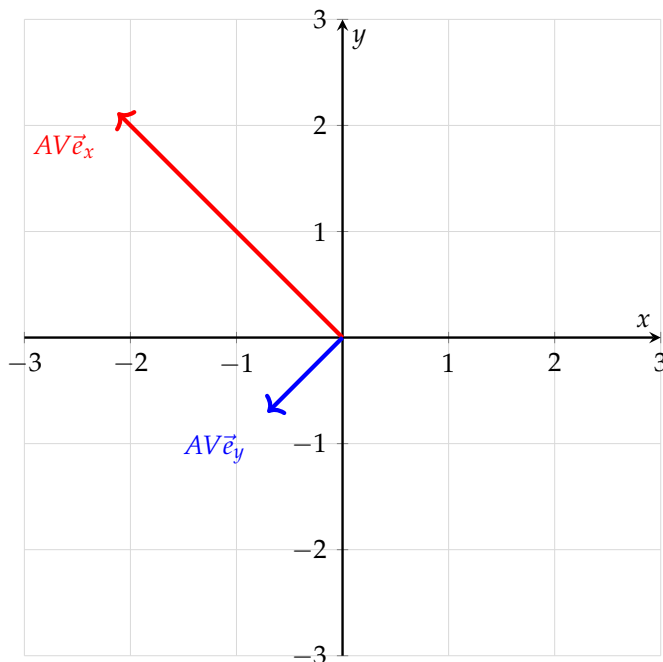
$$V = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \quad (7)$$

We will try to deduce  $U$  and  $\Sigma$  graphically, and then confirm our results numerically. **Plot the transformation given by  $V$  by showing how it affects  $\vec{e}_x$  and  $\vec{e}_y$  via left multiplication.** (HINT: Try writing  $V$  as a rotation matrix with a specific  $\theta$ .)

**Solution:** We notice that  $V$  is a rotation matrix with  $\theta = 45^\circ$ . Hence, it will rotate  $\vec{e}_x$  and  $\vec{e}_y$  by  $45^\circ$  counterclockwise.



(d) Suppose you are told that the transformation of  $AV$  on  $\vec{e}_x$  and  $\vec{e}_y$  looks like



**Write this transformation  $AV$  in terms of  $U$  and  $\Sigma$ .** Recall that the  $U$  matrix is an orthonormal

matrix so it will correspond to any rotations or reflections, and the  $\Sigma$  matrix is a diagonal matrix and will perform any scaling operations. **Based on this fact and the plot of the transformation above, write down a guess for what  $U$  and  $\Sigma$  might be.**

**Solution:** We notice that  $AV = U\Sigma$  by right multiplying our SVD by  $V$ . Now, it is reasonable to assume that, since  $AV\vec{e}_x$  appears 3 times as long as  $AV\vec{e}_y$ , then  $\Sigma = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$ . Furthermore, it appears as if the vectors have been rotated by  $135^\circ$  so it is likely that  $U$  is a rotation matrix with  $\theta = 135^\circ$ , i.e.,  $U = \begin{bmatrix} -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$ .

- (e) **Based on the given  $V$  matrix, compute the SVD.** Does your answer match your hypothesis from the previous part?

**Solution:** We can compute  $\Sigma$  and  $U$  as follows:

$$A\vec{v}_1 = \sigma_1\vec{u}_1 \quad (8)$$

$$A\vec{v}_2 = \sigma_2\vec{u}_2 \quad (9)$$

More explicitly,

$$A\vec{v}_1 = \begin{bmatrix} -1 & -2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} -\frac{3}{\sqrt{2}} \\ \frac{3}{\sqrt{2}} \end{bmatrix} \quad (10)$$

$$A\vec{v}_2 = \begin{bmatrix} -1 & -2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix} \quad (11)$$

We can set  $\sigma_1 = \|A\vec{v}_1\| = 3$  and  $\sigma_2 = \|A\vec{v}_2\| = 1$ . These choices yield  $\vec{u}_1 = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$  and

$\vec{u}_2 = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$ . Hence,

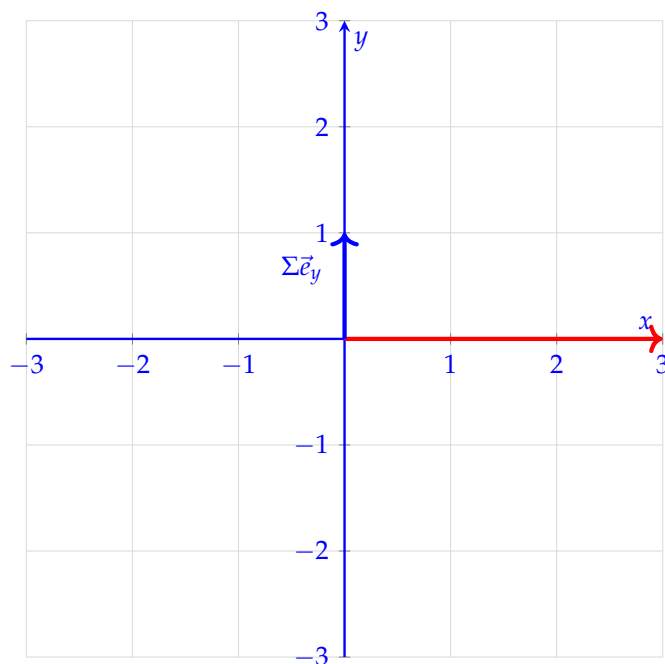
$$\Sigma = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \quad (12)$$

$$U = \begin{bmatrix} -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix} \quad (13)$$

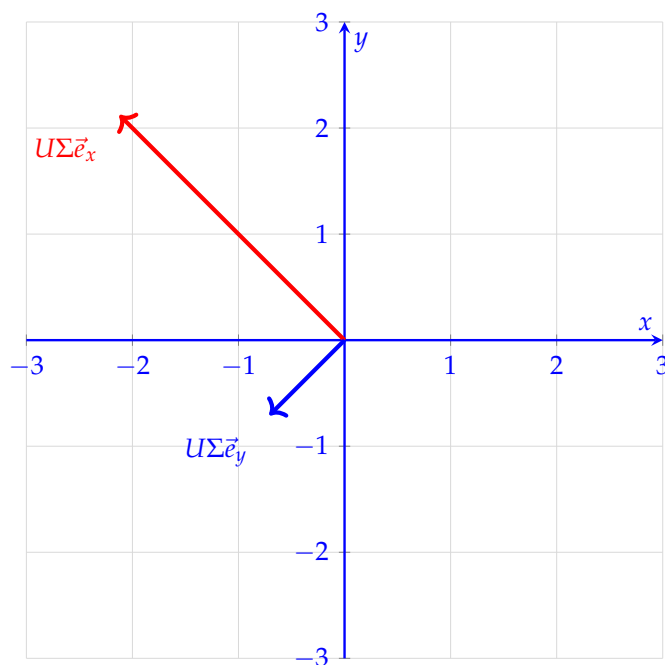
We notice that  $U$  is a rotation matrix with  $\theta = 135^\circ$ , and indeed, this matches with the  $U$  and  $\Sigma$  we hypothesized in the previous part.

- (f) **Using your answer for  $U$  and  $\Sigma$  from the previous part, plot the transformation of  $\Sigma$  on  $\vec{e}_x$  and  $\vec{e}_y$ . From here, plot the transformation of  $U\Sigma$  on  $\vec{e}_x$  and  $\vec{e}_y$ .** Does the final plot resemble the transformation shown by  $AV$ ?

**Solution:** We notice that  $\Sigma\vec{e}_x = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$  and  $\Sigma\vec{e}_y = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ . Hence, we get the following plot:



Now, we noticed that  $U$  is a rotation matrix with  $\theta = 135^\circ$  so this will rotate the graph above by  $135^\circ$ . This yields



which exactly matches what was given above.

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