

EECS 16B

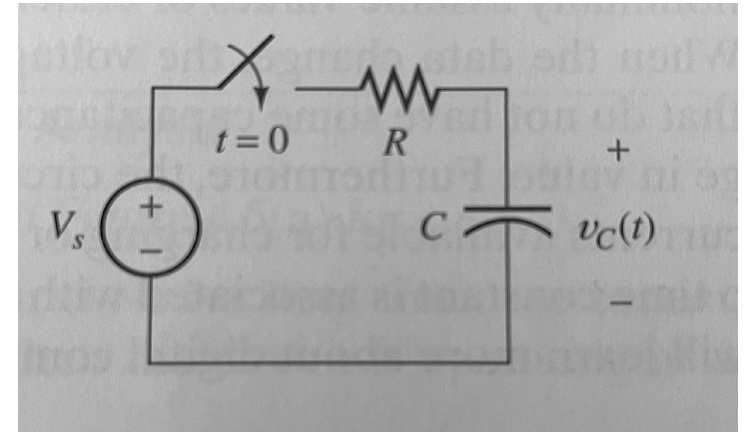
Designing Information Devices and Systems II
Lecture 3

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Recap: R-C circuits: Response in time

We now ask a slightly different question. What happens if a capacitor that had initially no charge is connected to a constant voltage at $t=0$

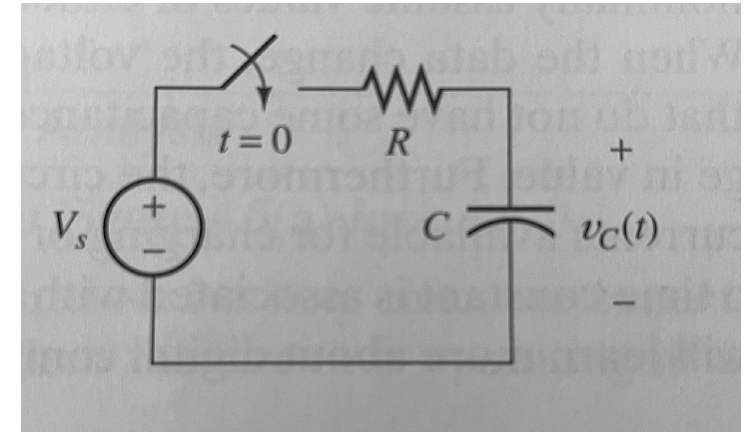


Transient Response

- Outline
 - R-C circuits
 - R-L circuits
 - R-L-C Circuits

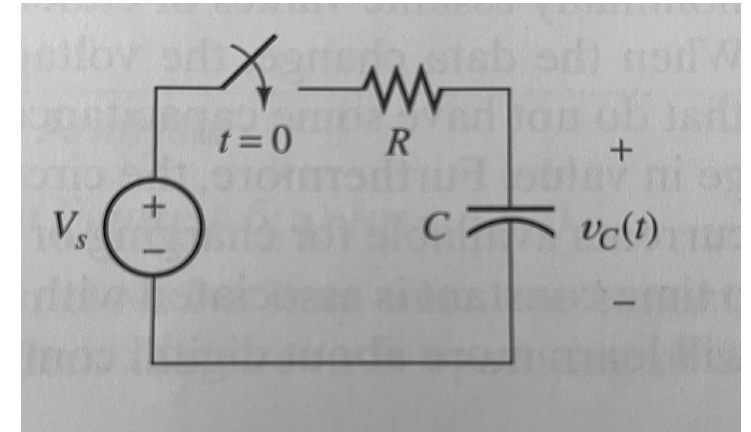
R-C circuits: Response in time

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R-C circuits: Response in time

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General Solution of the Differential Equation

For a first order, linear differential equation of the form

$$\frac{dy}{dt} + ay(t) = b(t) \quad \text{where we assume } a \text{ to be a constant}$$

Homogeneous/Complementary solution

$$\begin{aligned} \frac{dy}{dt} + ay(t) &= 0 \\ \Rightarrow \frac{dy}{y} &= -a \\ \Rightarrow \ln(y) &= -at + C \\ \Rightarrow y(t) &= Ke^{-at} \end{aligned}$$

Particular Solution (Integrating Factor Method):

$$\frac{dy}{dt} + ay(t) = b(t)$$

We want to find a multiplier function $f(t)$ such that

$$f(t) \frac{dy}{dt} + af(t)y(t) = b(t)f(t)$$

can be written as

$$\frac{d}{dt} [y(t)f(t)] = b(t)f(t) \quad \text{--(A)}$$

For equation (A) to hold

$$\begin{aligned} \frac{df(t)}{dt} &= af(t) \\ \Rightarrow f(t) &= e^{at} \end{aligned}$$

Then from (A)

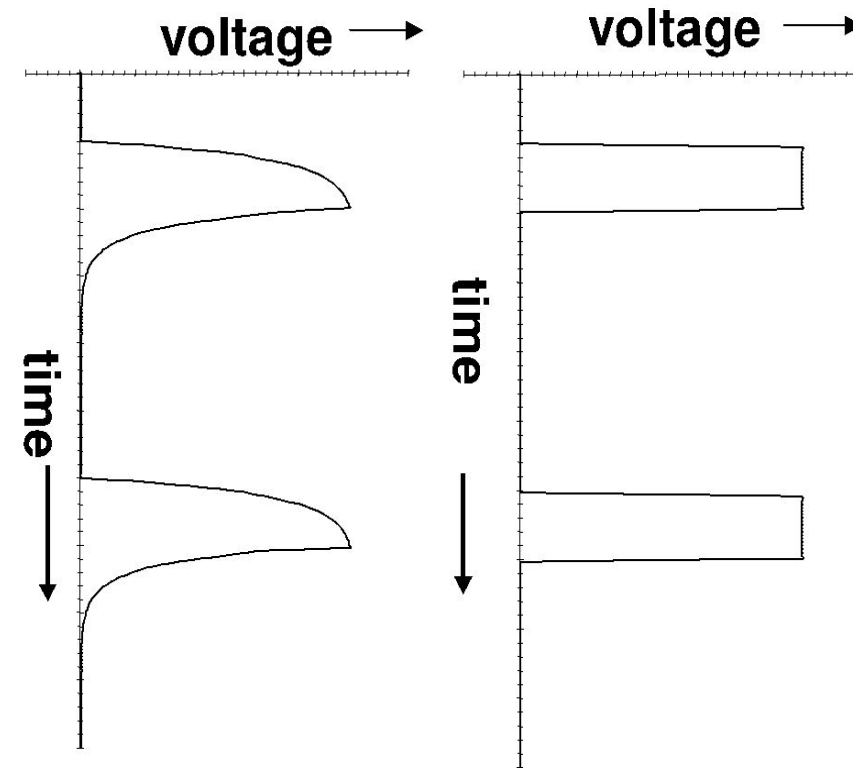
$$\begin{aligned} y(t) &= \frac{1}{f(t)} \int b(t)f(t)dt \\ \Rightarrow y_p(t) &= e^{-at} \int e^{at}b(t)dt \end{aligned}$$

$$\boxed{y(t) = Ke^{-at} + e^{-at} \int e^{at}b(t)dt}$$

K is determined using initial condition

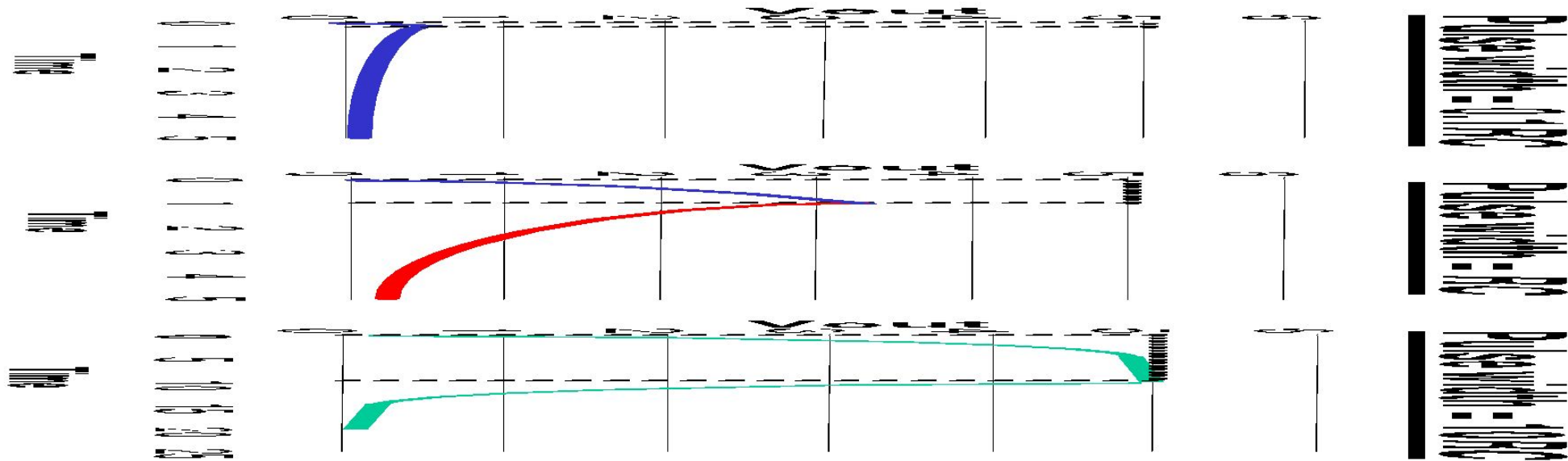
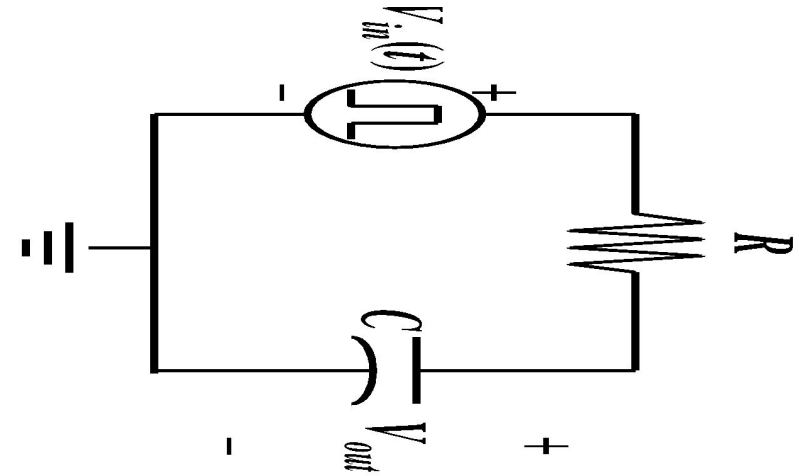
Digital Signals to a RC circuit

- Every node in a real circuit has capacitances
- Even if we send in very 'pure' square looking pulses what we actually get is how it looks in the right due to capacitor charging and discharging unless we go very very slow



Pulse Distortion

The input voltage pulse width must be large enough; otherwise the pulse is distorted

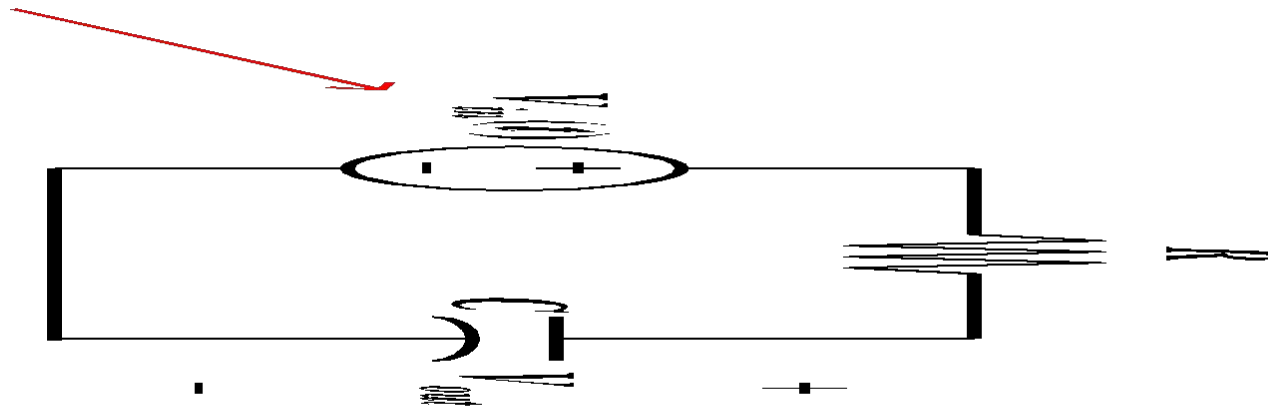


Computers are RC circuits (almost)

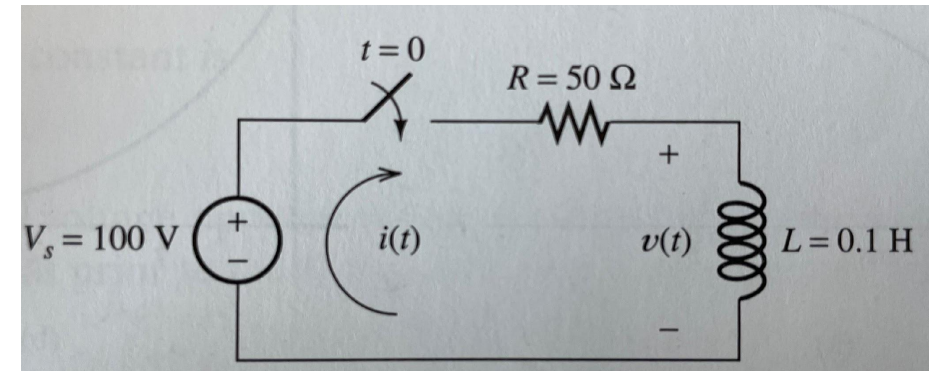
- Digital circuits are predominantly RC circuits (other than the communication part)
- Simplistically a logic gate can be model as a RC circuit
- The speed of the computer is limited by the RC time constant

switches between "low" (logic 0) and "high" (logic 1) voltage states

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R-L Circuits



Steady State

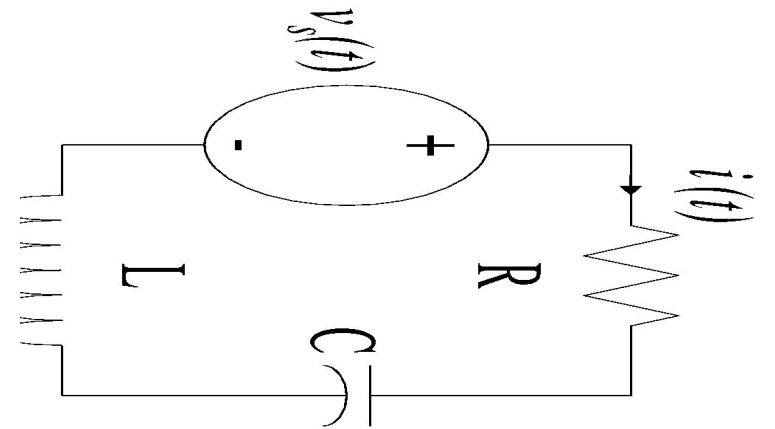
Capacitors:

Inductors:

Complex Numbers

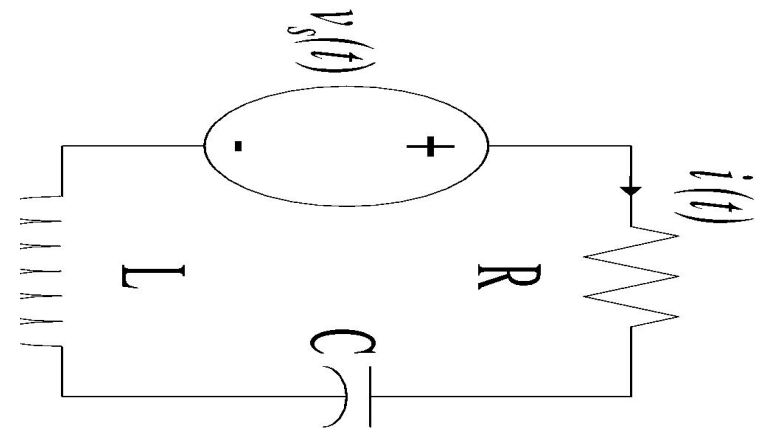
- $e^{i\theta} = \cos(\theta) + i\sin(\theta)$
- Read the note j

R-L-C circuits: Response in time



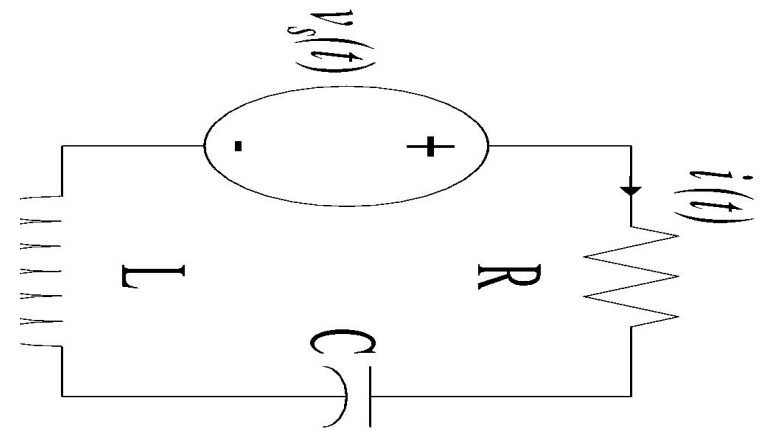
Filters, antennas, resonances

R-L-C circuits: Response in time



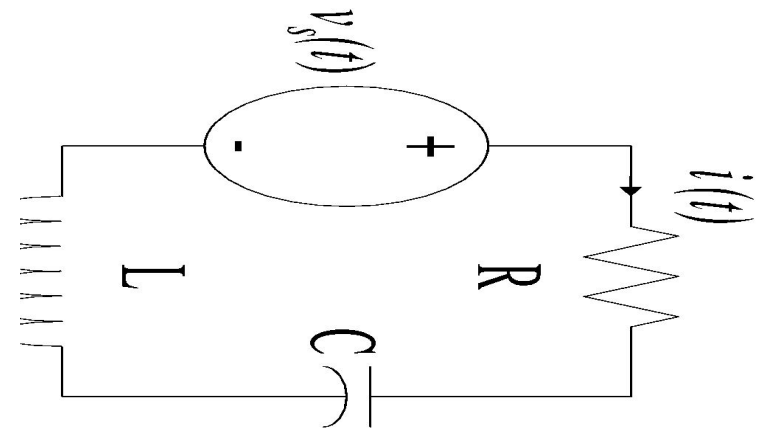
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Filters, antennas, resonances

Summary

- Overdamped – real unequal roots
- Critically damped – Real Equal roots
- Underdamped – Complex roots