

**EECS 16B**

# **Designing Information Devices and Systems II**

## **Lecture 10**

Prof. Sayeef Salahuddin

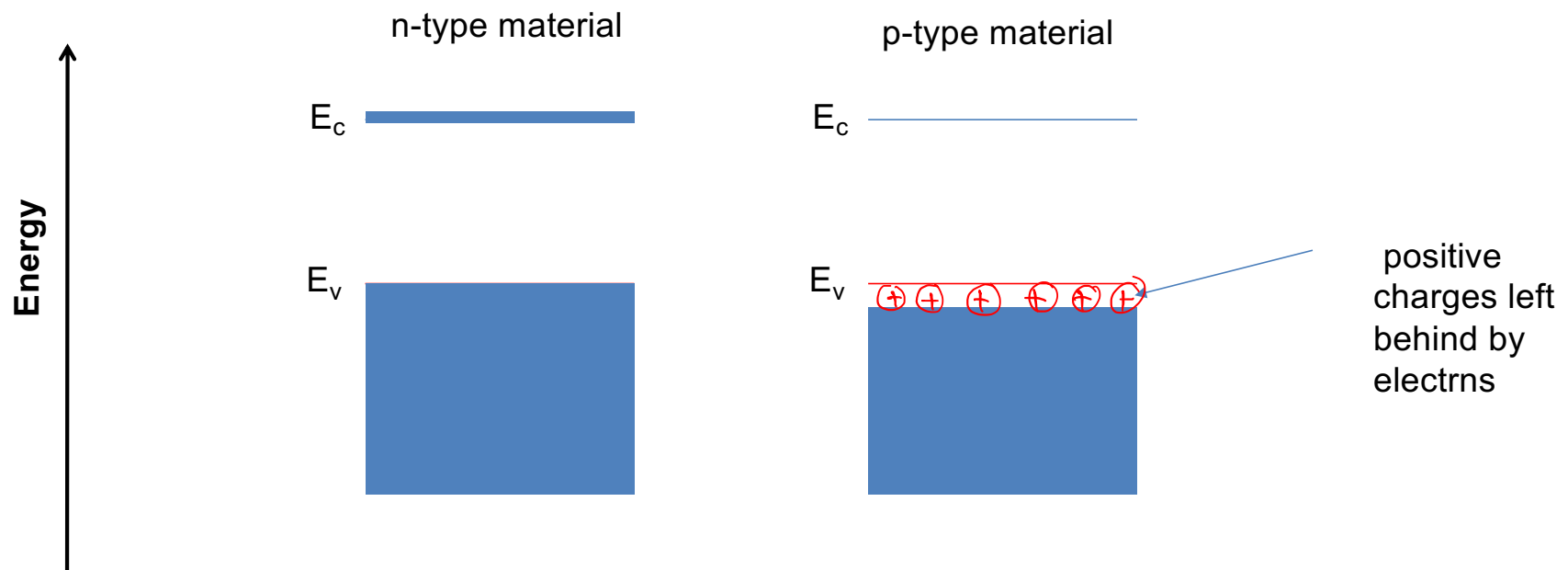
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# Devices

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- Outline
  - Amplifiers and Devices
  - Vector Differential Equations
- Reading-notes, slides

# Recap: N and P type Materials, Junctions and Devices

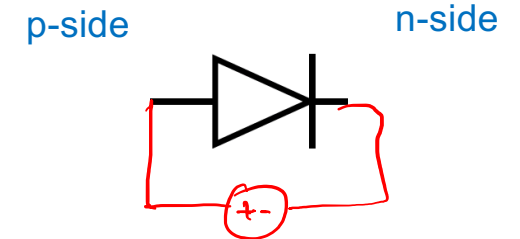
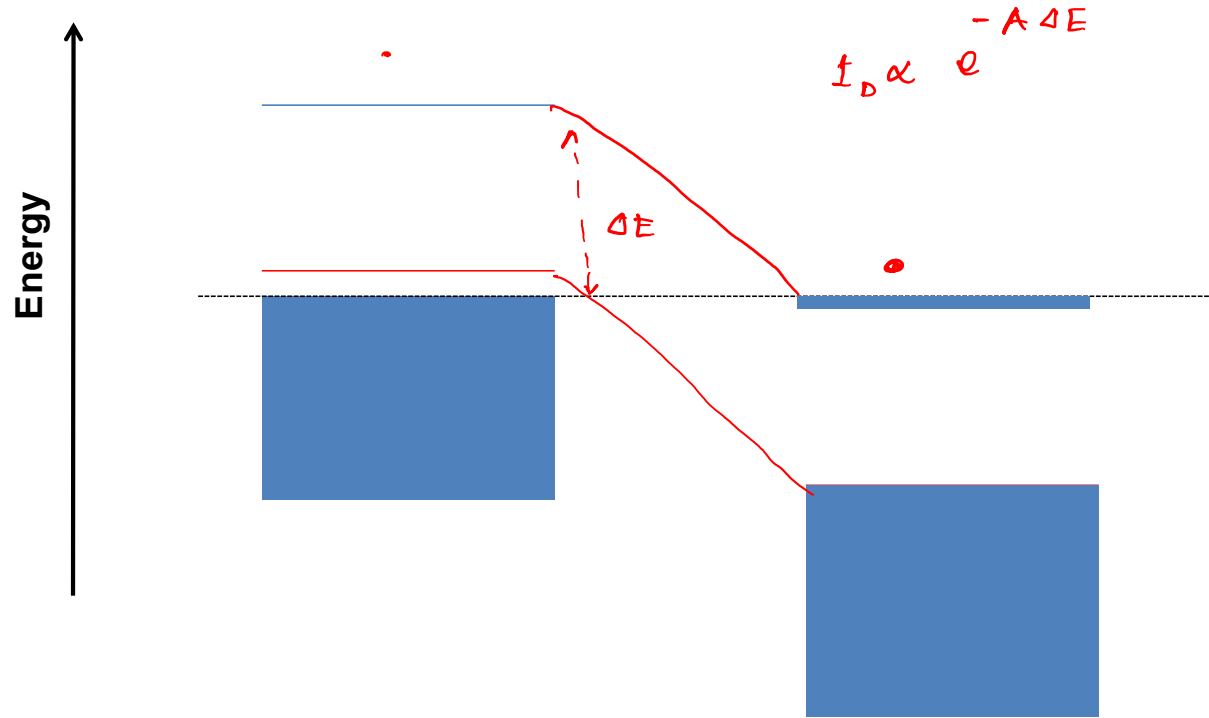


\*Blue color indicates electrons

# What does a voltage do?

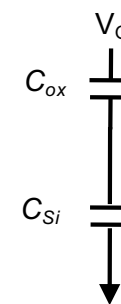
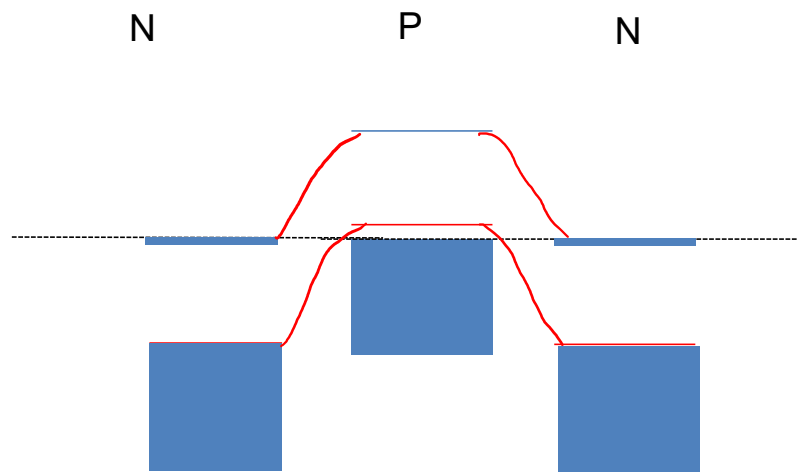
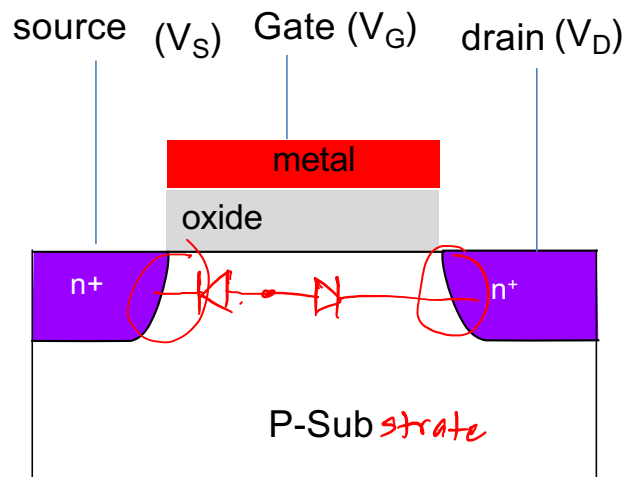
$$u = qv \\ = -eV$$

Qualitative Picture of a Junction Formation



Negative terminal of a battery brings electrons and thereby **increases energy**.

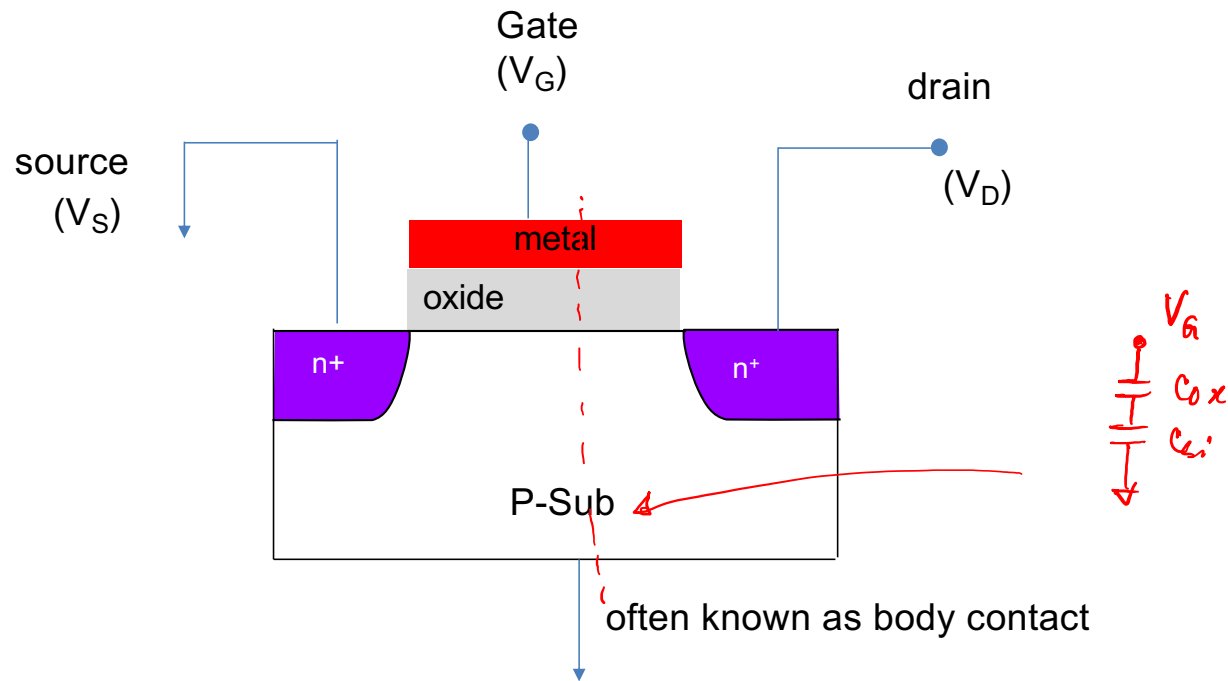
# Recap: Metal-Oxide-Semiconductor Field Effect Transistor (MOSFET)



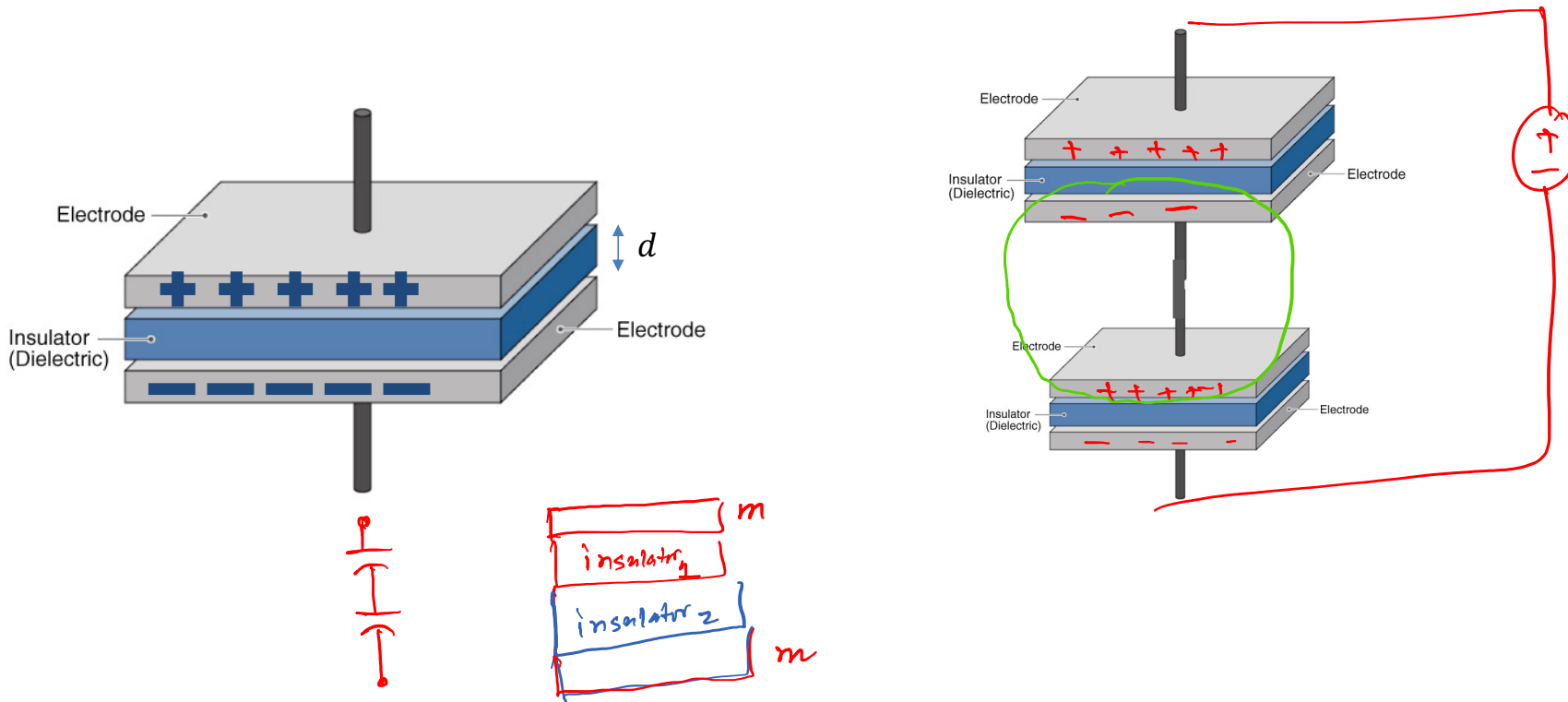
- + or – in the name of n or p type material indicates extent of doping. N+ means doped **heavily** to n type.
- In common MOSFET source and drain voltages are interchangeable

P-type semiconductor in the middle with little to no electrons on the conduction band acts like an insulator

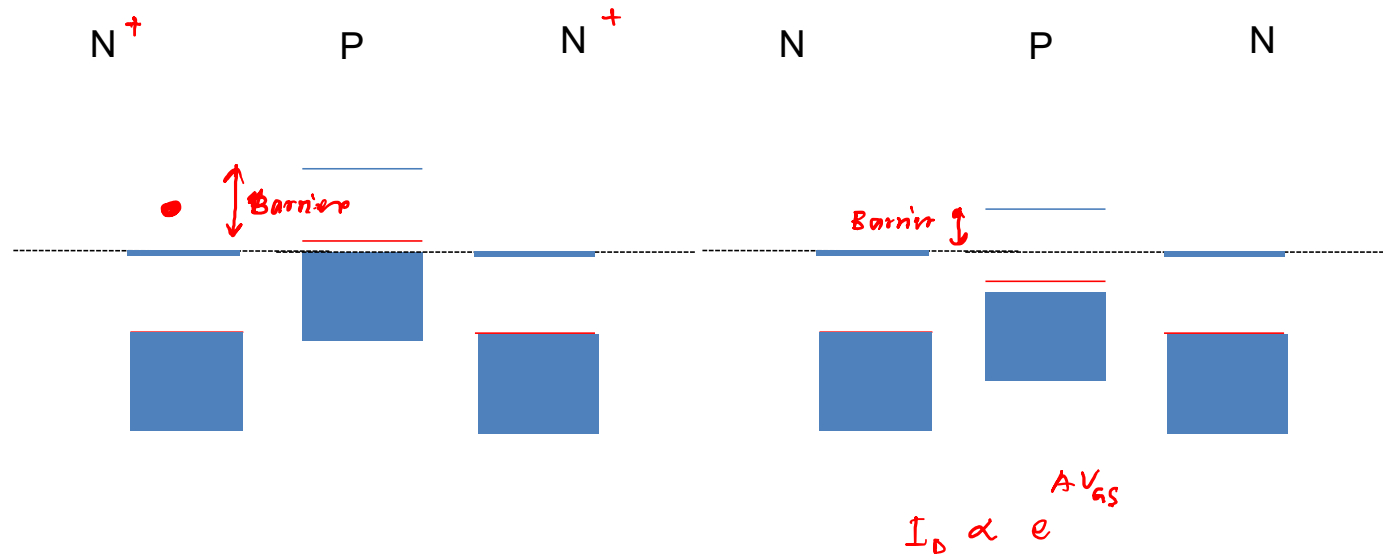
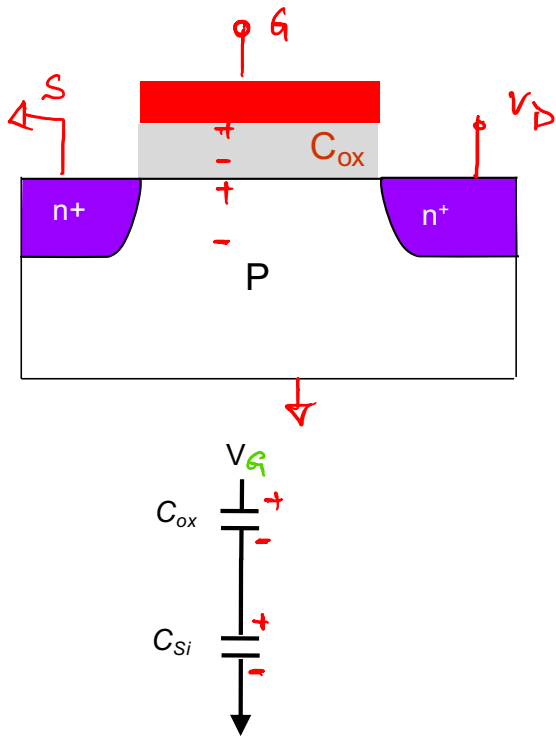
# MOSFET connections



# Recap: Capacitors (Review)

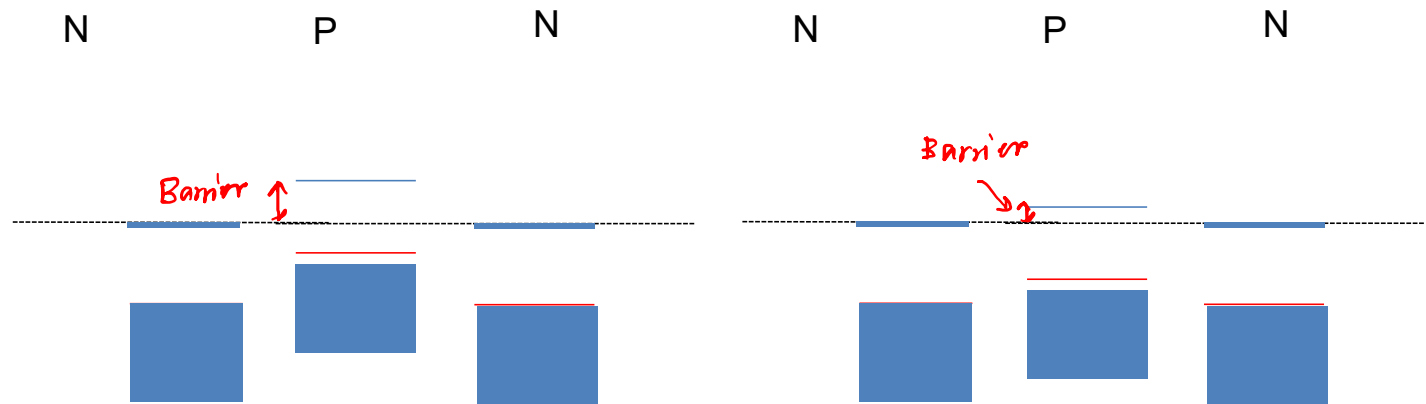
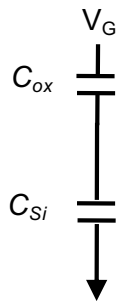
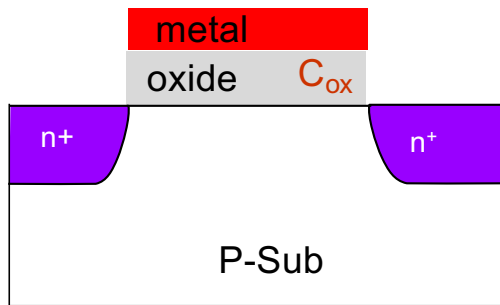


# MOSFET



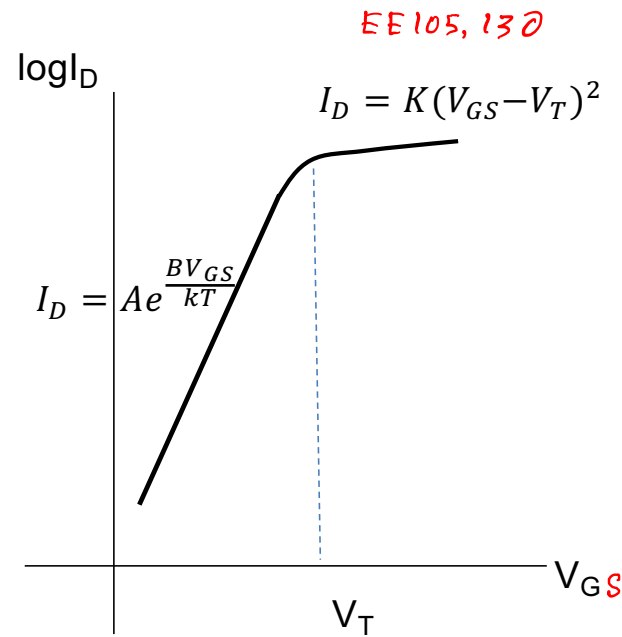
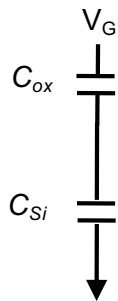
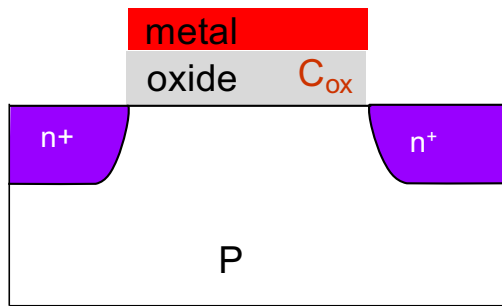


# MOSFET



At large gate voltages, one reaches close to maximum charge density achievable in Si. So rate of change in increase in electron density with gate voltage slows down

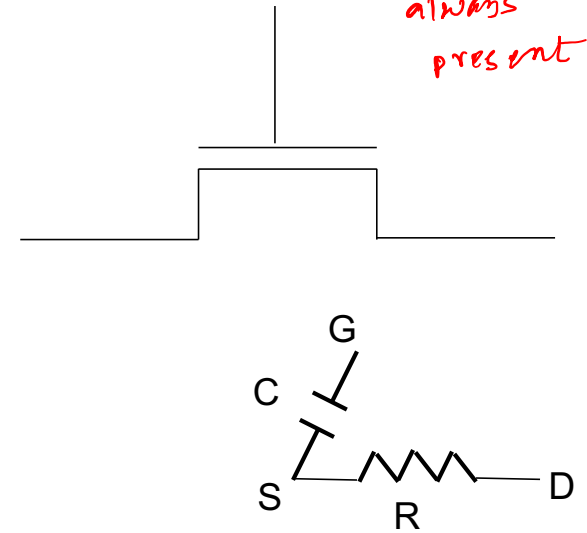
# MOSFETs



$V_T \equiv$  Threshold voltage

Assuming large  $V_{DS}$  is present

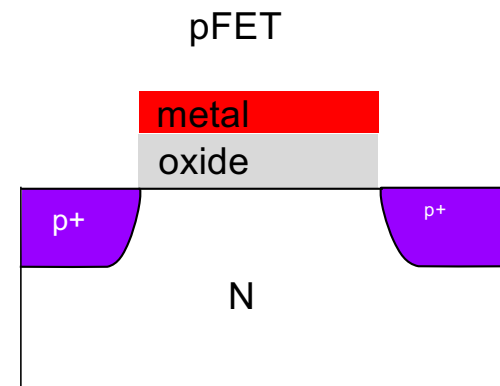
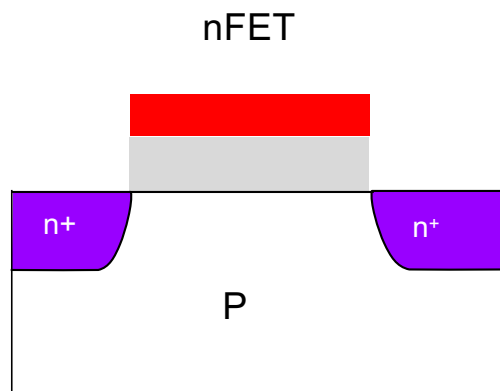
Assuming a sufficient  $V_{DS}$  is always present



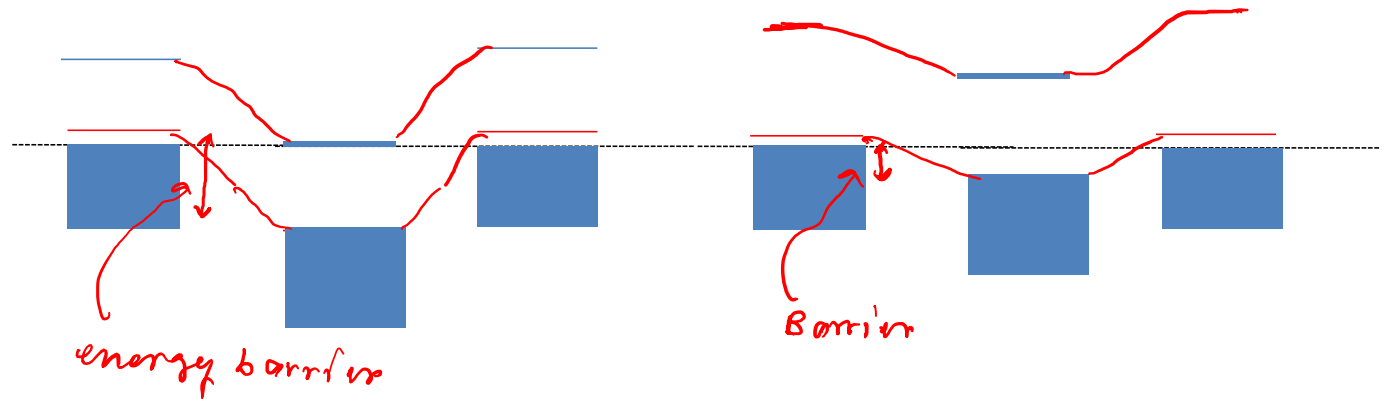
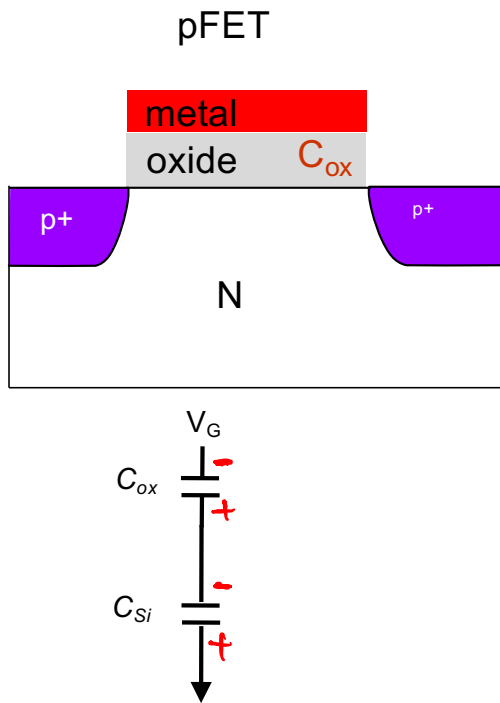
- C is the series combination of  $C_{ox}$  and  $C_{si}$
- $R = [I_{DS}/V_{DS}]^{-1}$

# nFET vs pFET

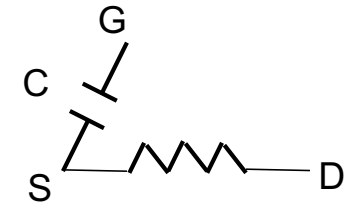
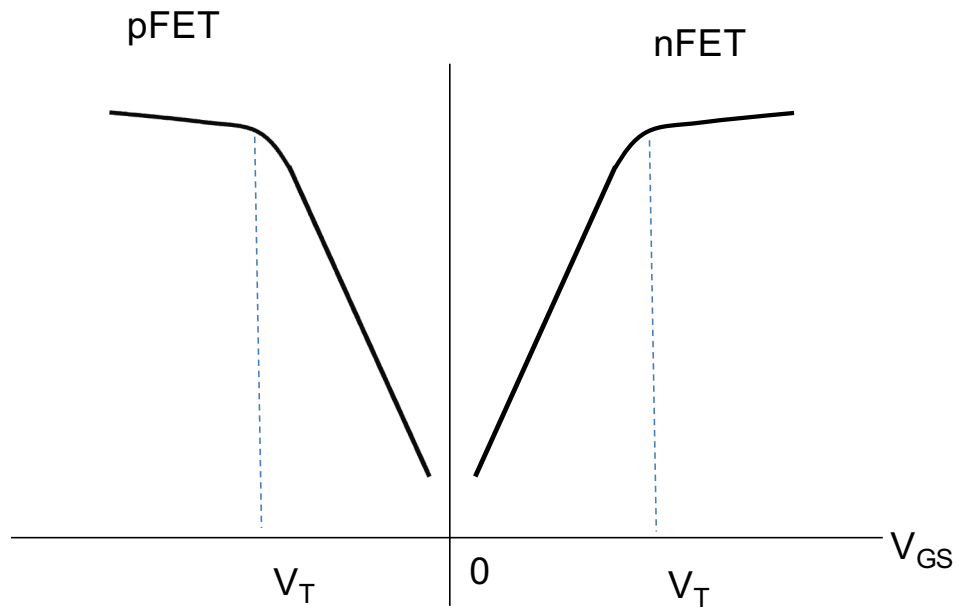
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# nFET vs pFET



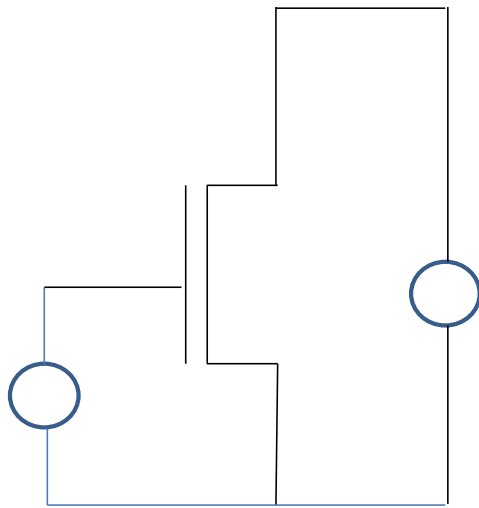
# nFET vs pFET



- nFET,  $V_{GS}$  and  $V_T$  are positive
- pFET,  $V_{GS}$  and  $V_T$  are negative

# FET as an analog amplifier

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When  $V_{GS} < V_T$

$$I_D = A e^{\frac{BV_{GS}}{kT}}$$

Small change in  $V_{GS}$  changes  $I_D$  exponentially

When  $V_{GS} > V_T$

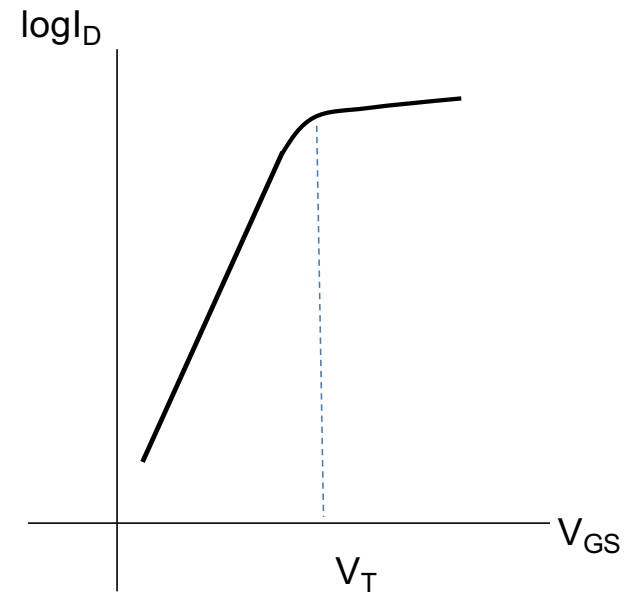
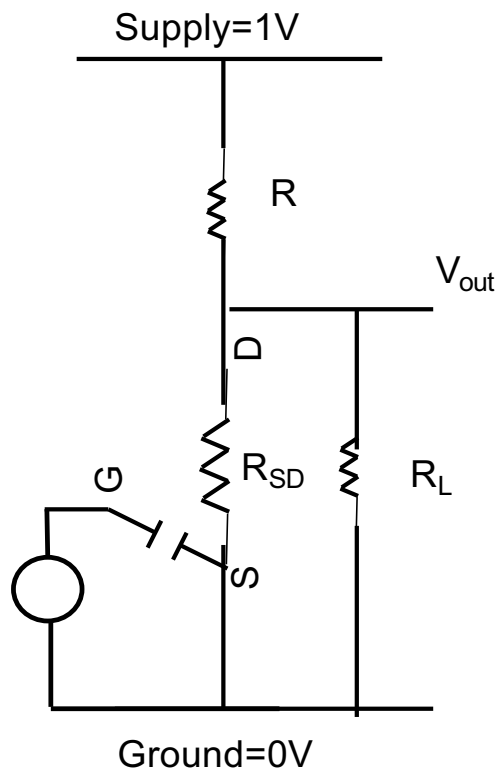
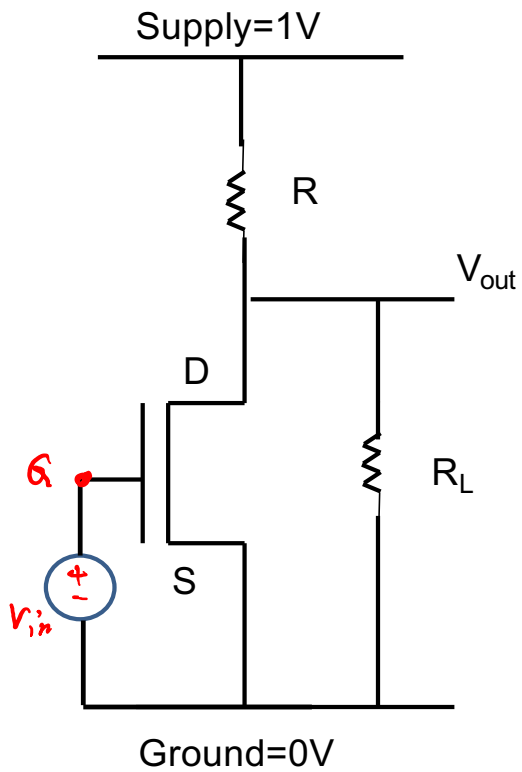
$$I_D = K(V_{GS} - V_T)^2$$

Small change in  $V_{GS}$  changes  $I_D$  quadratically

Overall, Large changes in the Drain current can be achieved by changing Gate Voltage

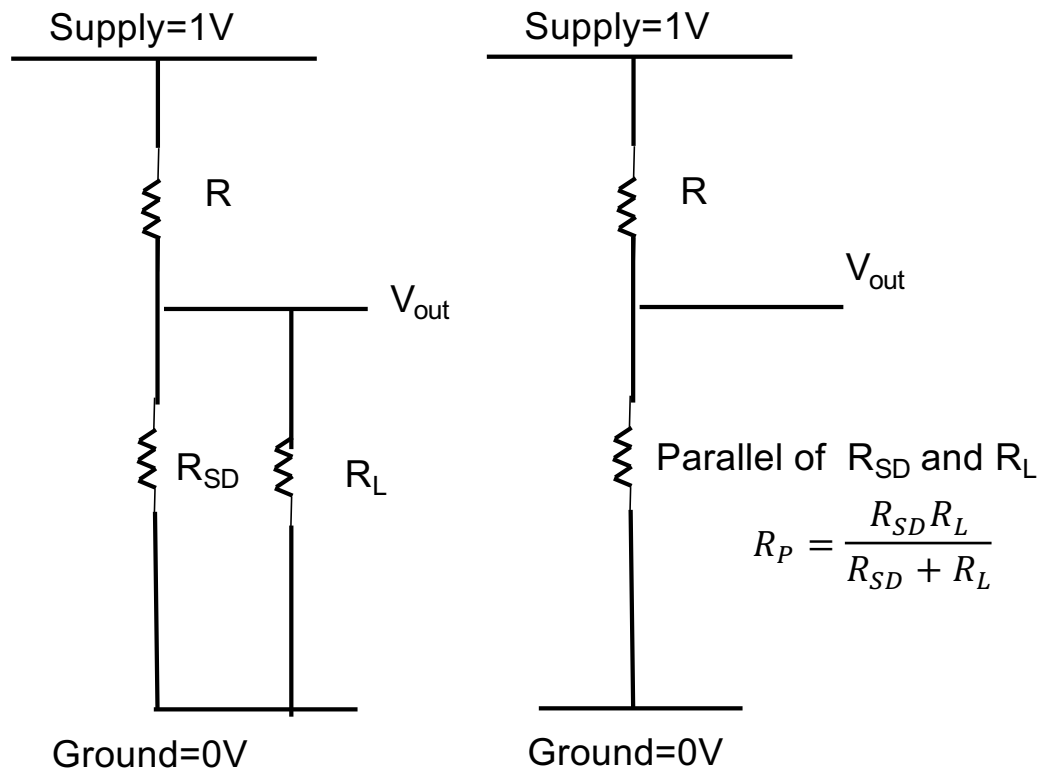
The parameter that is used to quantify the amplification is called **Transconductance**  $g_m = \frac{dI_D}{dV_{GS}}$

# FET in digital logic



When  $V_{GS}$  is High,  $R_{SD}$  is low  
 When  $V_{GS}$  is Low,  $R_{SD}$  is High

# FET in digital logic



$$V_{out} = \frac{R_P}{R + R_P} V_{supply}$$

When  $R_{SD} \ll R_L$  i.e.,  $V_{GS}$  is high

$$R_P = \frac{R_{SD} R_L}{R_{SD} + R_L} \approx \frac{R_{SD}}{R_L} \approx 0$$

$$V_{out} \approx 0$$

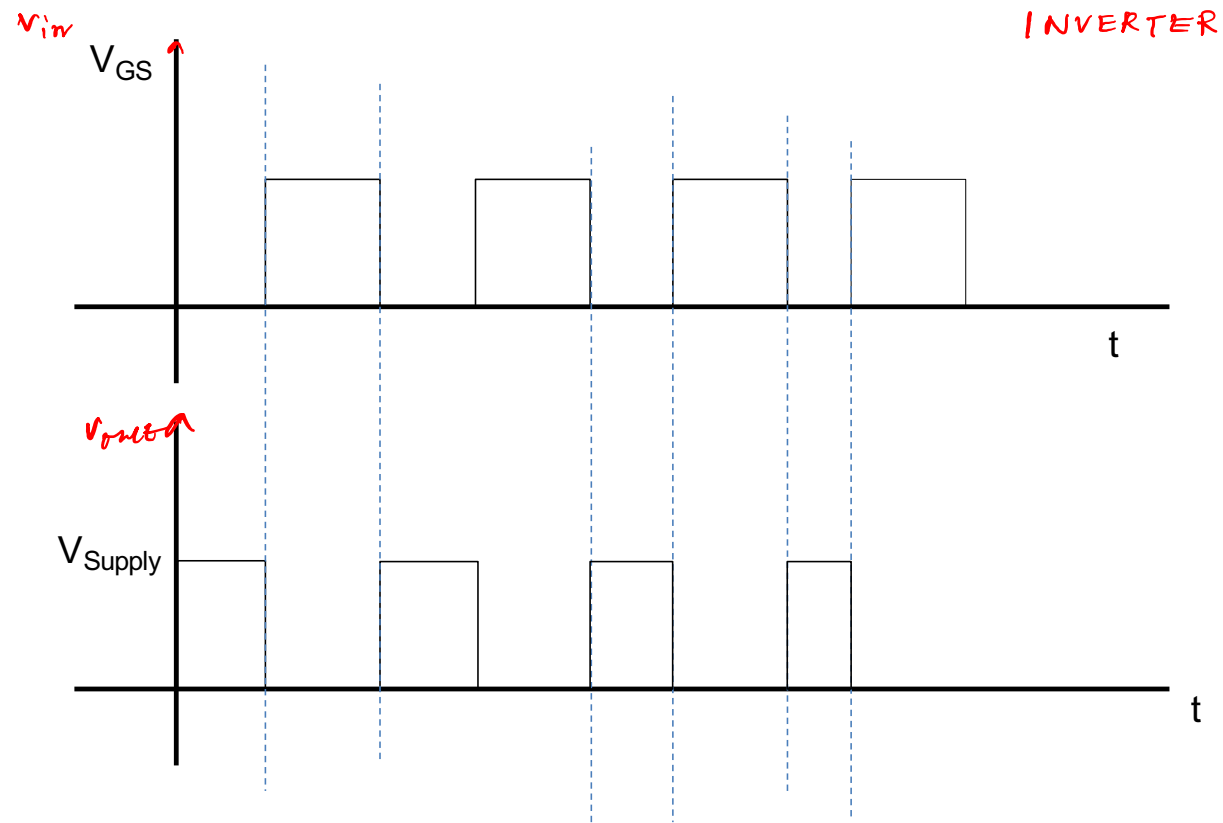
When  $R_{SD} \gg R_L$ ; i.e. when  $V_{GS}$  is low

$$R_P = \frac{R_{SD} R_L}{R_{SD} + R_L} \approx R_L$$

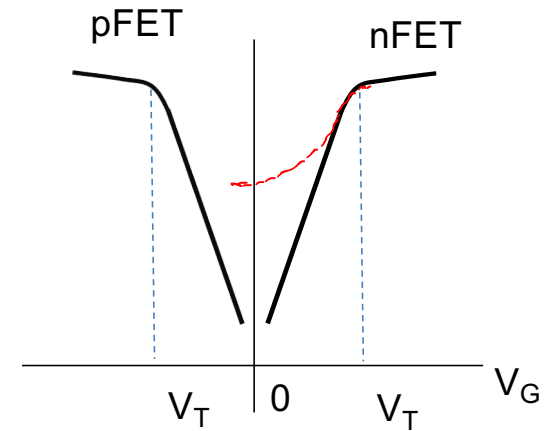
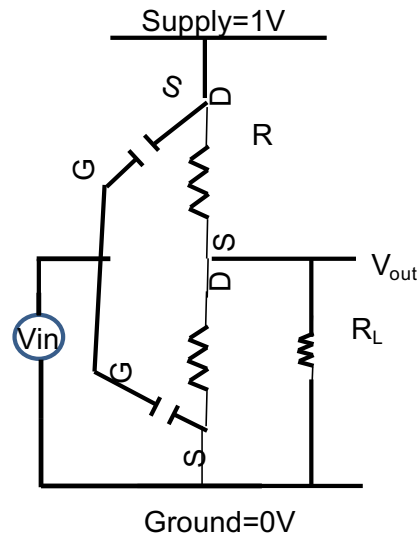
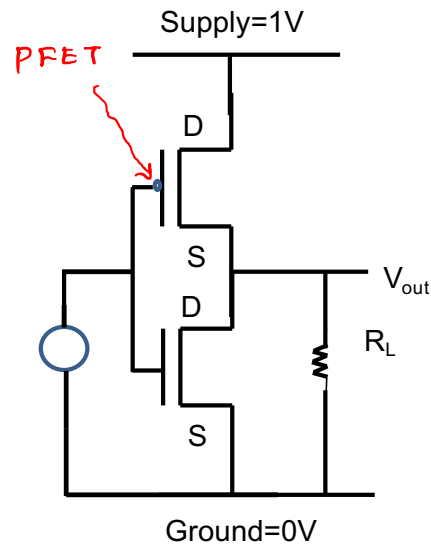
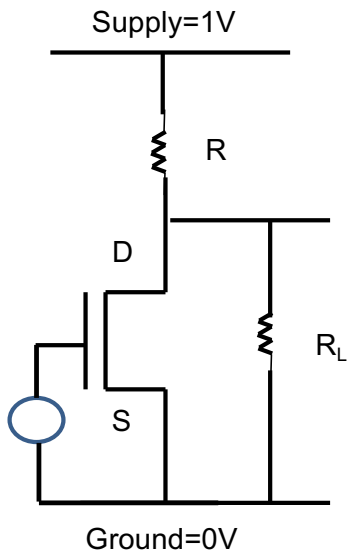
$$V_{out} \approx \frac{R_L}{R + R_L} V_{supply} \approx V_{supply} \text{ if } R_L \gg R$$



# FET in digital logic



# CMOS (complimentary mos)



**Vin=1V**

$V_{GS}$  for nFET is HIGH  $\rightarrow R_{SD}$  is LOW

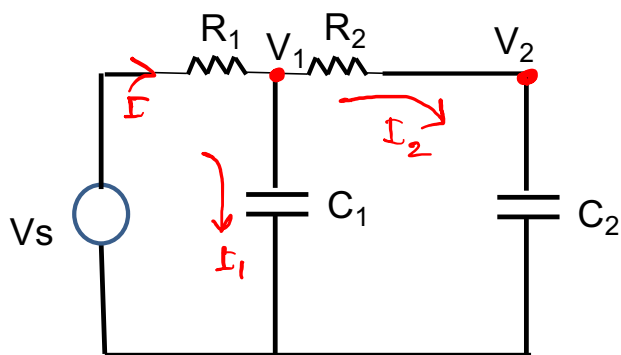
$V_{GS}$  for pFET is LOW  $\rightarrow R_{SD}$  is high

**Vin=0 V**

$V_{GS}$  for nFET is LOW  $\rightarrow R_{SD}$  is HIGH

$V_{GS}$  for pFET is HIGH **NEGATIVE**  $\rightarrow R_{SD}$  is LOW

# Vector Differential Equations



$$V_1 = I_2 R_2 + V_2 = R_2 C_2 \frac{dV_2}{dt} + V_2$$

$$\frac{dV_2}{dt} = \frac{1}{R_2 C_2} V_1 - \frac{1}{R_2 C_2} V_2$$

*Substitute*

$$V_s - V_1 = I R_1 \quad ; \quad I = I_1 + I_2 = C_1 \frac{dV_1}{dt} + C_2 \frac{dV_2}{dt}$$

$$V_s - V_1 = (C_1 \frac{dV_1}{dt} + C_2 \frac{dV_2}{dt}) R_1$$

$$R_2 (V_s - V_1) = (R_2 C_1 \frac{dV_1}{dt} + R_2 C_2 \frac{dV_2}{dt}) R_1$$

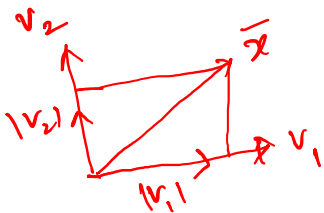
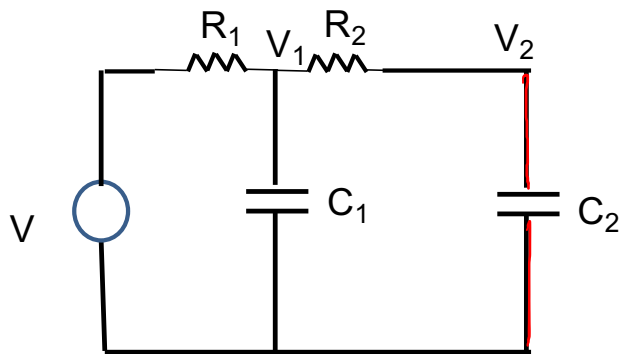
$$\frac{dV_1}{dt} = -\left(\frac{1}{R_2 C_1} + \frac{1}{R_1 C_1}\right) V_1 + \frac{1}{R_2 C_1} V_2 + \frac{1}{R_1 C_1} V_s$$

$$\frac{dV_2}{dt} = \frac{1}{R_2 C_2} V_1 - \frac{1}{R_2 C_2} V_2$$

$$\frac{dV_1}{dt} = -\frac{1 + \frac{R_2}{R_1}}{R_2 C_1} V_1 + \frac{1}{R_2 C_1} V_2 + \frac{1}{R_1 C_1} V_s$$

$$\frac{dV_1}{dt} = -\left(\frac{1}{R_2 C_1} + \frac{1}{R_1 C_1}\right) V_1 + \frac{1}{R_2 C_1} V_2 + \frac{1}{R_1 C_1} V_s$$

# Vector Differential Equations



$$\frac{dV_1}{dt} = -\left(\frac{1}{R_2 C_1} + \frac{1}{R_1 C_1}\right) V_1 + \frac{1}{R_2 C_1} V_2 + \frac{1}{R_1 C_1} V_s$$

$$\frac{dV_2}{dt} = \frac{1}{R_2 C_2} V_1 - \frac{1}{R_2 C_2} V_2$$

$$\frac{d}{dt} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \underbrace{\begin{bmatrix} -\left(\frac{1}{R_2 C_1} + \frac{1}{R_1 C_1}\right) & \frac{1}{R_2 C_1} \\ \frac{1}{R_2 C_2} & -\frac{1}{R_2 C_2} \end{bmatrix}}_{\mathbf{A}} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} + \begin{bmatrix} \frac{1}{R_1 C_1} V_s \\ 0 \end{bmatrix}$$

$$\frac{d}{dt} \bar{x} = \mathbf{A} \bar{x} + \bar{b}$$

Vector differential equation

$$\bar{x} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$$

$$\bar{b} = \begin{bmatrix} \frac{1}{R_1 C_1} V_s \\ 0 \end{bmatrix}$$

$$\frac{dy}{dt} = ay + b$$

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$$\frac{d}{dt} \bar{x} = A \bar{x} + \bar{b}$$

$$\bar{b} = B \bar{u}$$

↓  
Matrix

$$\frac{d}{dt} \bar{x} = A \bar{x} + B \bar{u}$$

$$\begin{bmatrix} x & x & x \\ x & x & x \\ x & x & x \end{bmatrix} \xRightarrow{\text{Diagonalization}} \begin{bmatrix} x & & \\ & x & \\ & & x \end{bmatrix}$$