

**EECS 16B**

# **Designing Information Devices and Systems II**

## **Lecture 17**

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# Outline

- Condition for Controllability
- Orthonormal Bases
- Orthonormalization (Gram-Schmidt procedure)

# Controllability

**Definition:** a system  $\vec{x}[i + 1] = A\vec{x}[i] + Bu[i]$  is said to be **controllable** if given any target state  $\vec{x}_f \in \mathbb{R}^n$  and initial state  $\vec{x}[0]$ , we can find a time  $i = \ell$  and a sequence of control input  $u[0], \dots, u[\ell]$  such that  $\vec{x}[\ell] = \vec{x}_f$

$$\mathcal{C}_\ell \doteq [A^{\ell-1}B \mid \dots \mid AB \mid B] \in \mathbb{R}^{n \times \ell} \quad \vec{x}[\ell] = A^\ell \vec{x}[0] + \mathcal{C}_\ell \vec{u}[\ell]$$

**Condition for Controllability:**  $\text{span}[\mathcal{C}_\ell] = \mathbb{R}^n$  or  $\text{rank}[\mathcal{C}_\ell] = n$

# Controllability

**Lemma:** Consider  $\mathcal{C}_\ell \doteq [A^{\ell-1}B \mid \cdots \mid AB \mid B] \in \mathbb{R}^{n \times \ell}$

If  $\text{rank}[\mathcal{C}_{\ell+1}] = \text{rank}[\mathcal{C}_\ell]$  then  $\text{rank}[\mathcal{C}_m] = \text{rank}[\mathcal{C}_\ell]$  for all  $m \geq \ell + 1$

**Proof:**

# Controllability

**Lemma:** Consider  $\mathcal{C}_\ell \doteq [A^{\ell-1}B \mid \cdots \mid AB \mid B] \in \mathbb{R}^{n \times \ell}$

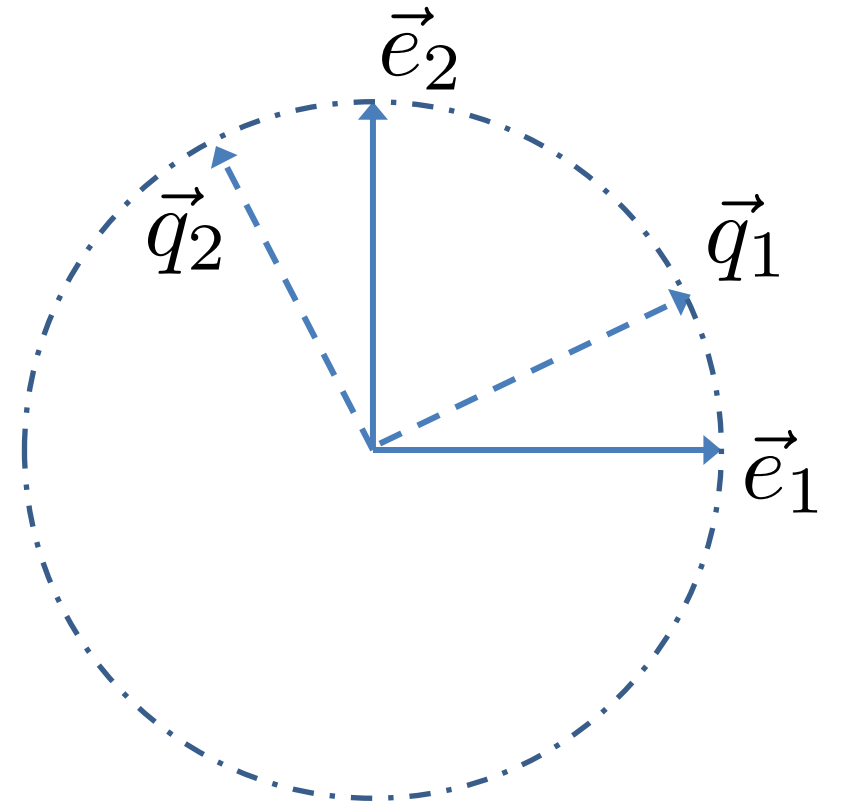
If  $\text{rank}[\mathcal{C}_{\ell+1}] = \text{rank}[\mathcal{C}_\ell]$  then  $\text{rank}[\mathcal{C}_m] = \text{rank}[\mathcal{C}_\ell]$  for all  $m \geq \ell + 1$

# Orthonormal Bases and Matrix

**Definition:** A set of vectors as columns of a matrix  $Q = [\vec{q}_1, \vec{q}_2, \dots, \vec{q}_k] \in \mathbb{R}^{n \times k}$  are said to be **orthonormal** if

$$\vec{q}_i^\top \vec{q}_j = \begin{cases} 0 & \text{if } i \neq j \quad (\text{orthogonal}) \\ 1 & \text{if } i = j \quad (\text{normalized}) \end{cases}$$

# Orthonormal Bases and Matrix (Examples)



# Orthonormal Bases or Matrix: Properties

Isometric

Invertible (and determinate)

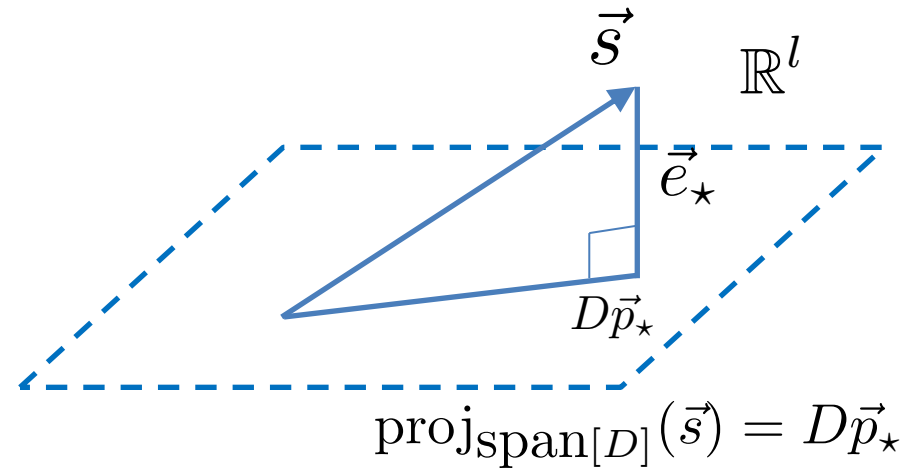
Multiplicative



# Orthonormal Bases: Projection

Least Squares:  $\vec{p}_\star = \arg \min_{\vec{p}} \|\vec{s} - D\vec{p}\|_2^2 = (D^\top D)^{-1} D^\top \vec{s}$

If  $D = [\vec{d}_1, \vec{d}_2, \dots, \vec{d}_k]$  orthonormal:  $D^\top D = I$



# Orthonormalization: QR Decomposition

What if columns of  $D = [\vec{d}_1, \vec{d}_2, \dots, \vec{d}_k]$  are not orthonormal? Consider the QR decomposition:

( $\text{rank}[D] = k$ )

$$[\vec{d}_1, \vec{d}_2, \dots, \vec{d}_k] = [\vec{q}_1, \vec{q}_2, \dots, \vec{q}_k] \begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1k} \\ 0 & r_{22} & \cdots & r_{2k} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & r_{kk} \end{bmatrix}$$

# QR Decomposition & Least Squares

# Gram-Schmidt Procedure

Gram-Schmidt via illustration:  $D = [\vec{d}_1, \vec{d}_2]$  in  $\mathbb{R}^2$

# Gram-Schmidt Procedure

Gram-Schmidt via algebraic derivation:  $D = [\vec{d}_1, \vec{d}_2, \dots, \vec{d}_k]$  in  $\mathbb{R}^n$

# Gram-Schmidt Procedure (Summary)

$$\vec{z}_1 = \vec{d}_1 \qquad \vec{q}_1 = \vec{z}_1 / \|\vec{z}_1\|$$

$$\vec{z}_2 = \vec{d}_2 - (\vec{d}_2^\top \vec{q}_1) \vec{q}_1 \qquad \vec{q}_2 = \vec{z}_2 / \|\vec{z}_2\|$$

$$\vec{z}_3 = \vec{d}_3 - (\vec{d}_3^\top \vec{q}_1) \vec{q}_1 - (\vec{d}_3^\top \vec{q}_2) \vec{q}_2 \qquad \vec{q}_3 = \vec{z}_3 / \|\vec{z}_3\|$$

⋮

⋮

$$\vec{z}_k = \vec{d}_k - \sum_{j=1}^{k-1} (\vec{d}_k^\top \vec{q}_j) \vec{q}_j \qquad \vec{q}_k = \vec{z}_k / \|\vec{z}_k\|$$

**Claim:** 1.  $\vec{z}_j^\top \vec{q}_i = 0$  for all  $i < j$     2.  $\|\vec{z}_i\| = \vec{d}_i^\top \vec{q}_i$

# Gram-Schmidt Procedure & QR

$$\vec{d}_1 = (\vec{d}_1^\top \vec{q}_1) \vec{q}_1$$

$$\vec{d}_2 = (\vec{d}_2^\top \vec{q}_1) \vec{q}_1 + (\vec{d}_2^\top \vec{q}_2) \vec{q}_2$$

$$\vec{d}_3 = (\vec{d}_3^\top \vec{q}_1) \vec{q}_1 + (\vec{d}_3^\top \vec{q}_2) \vec{q}_2 + (\vec{d}_3^\top \vec{q}_3) \vec{q}_3$$

⋮

$$\vec{d}_k = (\vec{d}_k^\top \vec{q}_1) \vec{q}_1 + (\vec{d}_k^\top \vec{q}_2) \vec{q}_2 + \cdots + (\vec{d}_k^\top \vec{q}_k) \vec{q}_k$$

$$[\vec{d}_1, \vec{d}_2, \dots, \vec{d}_k] = [\vec{q}_1, \vec{q}_2, \dots, \vec{q}_k]$$

$$\begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1k} \\ 0 & r_{22} & \cdots & r_{2k} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & r_{kk} \end{bmatrix}$$

$$(r_{ij} = \vec{d}_j^\top \vec{q}_i)$$