

**NTU 6342 / EE 241 Homework #3**  
**SOLUTIONS**

**Problem #1:**

Delay times:

$$t_{p\_FO4\_20} := 0.424\text{ns}$$

$$t_{p\_FO4\_100} := 2.12\text{ns}$$

Simulation values:

$$T_{\min} := 2 \cdot t_{p\_FO4\_20} \quad T_{\max} := 2 \cdot t_{p\_FO4\_100}$$

$$T_{\min} = 0.848 \text{ ns}$$

$$T_{\max} = 4.24 \text{ ns}$$

$$f_{\max} := \frac{1}{T_{\min}}$$

$$f_{\min} := \frac{1}{T_{\max}}$$

$$f_{\max} = 1.179 \text{ GHz}$$

$$f_{\min} = 235.849 \text{ MHz}$$

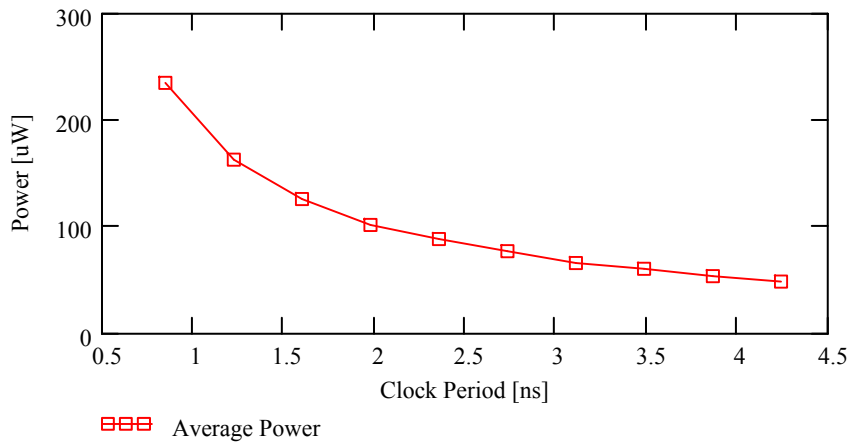
**Part a:**

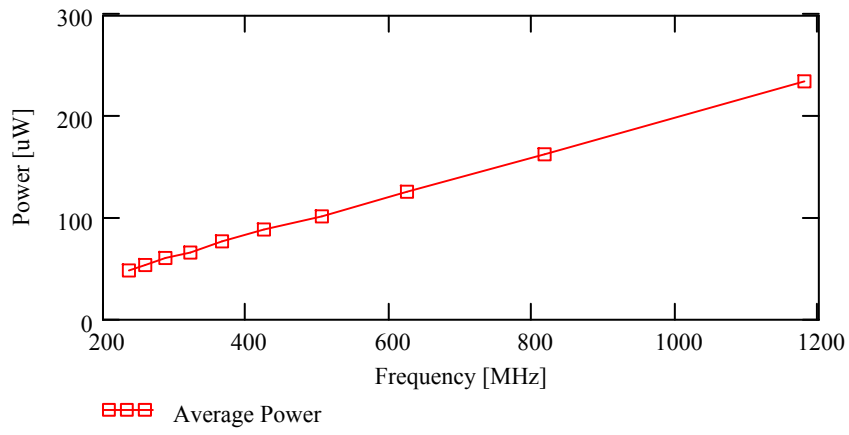
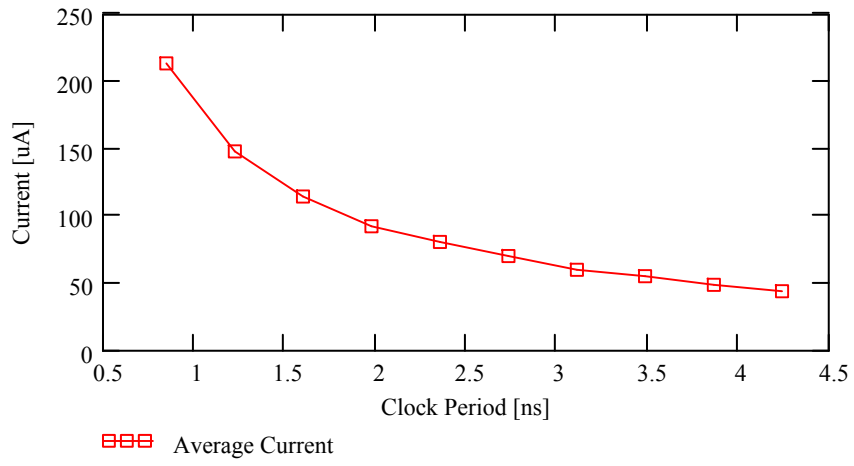
PartAData := READPRN("inverter\_delay\_fo4\_20.txt")

$$\text{PulseWidth} := \text{PartAData}^{(0)} \text{ s} \quad V_{\text{dd}} := 1.1\text{V} \quad I_{\text{ave}} := \text{PartAData}^{(2)} \text{ A}$$

$$\text{Frequency} := \frac{1}{2 \cdot \text{PulseWidth}}$$

$$P_{\text{ave}} := (|I_{\text{ave}}| \cdot V_{\text{dd}})$$

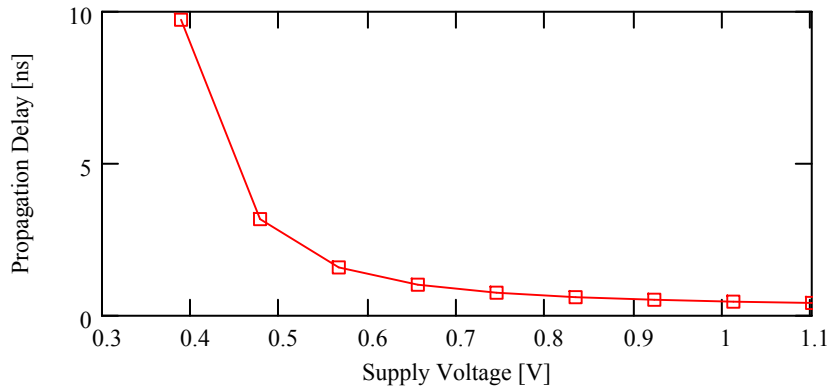




Part b:

PartBData := READPRN("inverter\_delay\_fo4\_20\_vdd.txt")

SupplyVoltage := PartBData<sup><0></sup> V      t<sub>p</sub> := PartBData<sup><4></sup> s



Interpolating the delay-Vdd curve to get the needed Vdd for a given delay:

$$V_{dd\_opt} := \begin{cases} \text{for } n \in 0..9 \\ x_n \leftarrow \text{linterp}\left(\frac{-t_p}{s}, \frac{\text{SupplyVoltage}}{V}, \frac{-\text{PulseWidth}_n}{s}\right) \\ x \cdot V \end{cases}$$

V <sub>dd_opt</sub> =	1.099	V
	0.841	
	0.731	
	0.667	
	0.631	
	0.602	
	0.573	
	0.559	
	0.548	
	0.537	

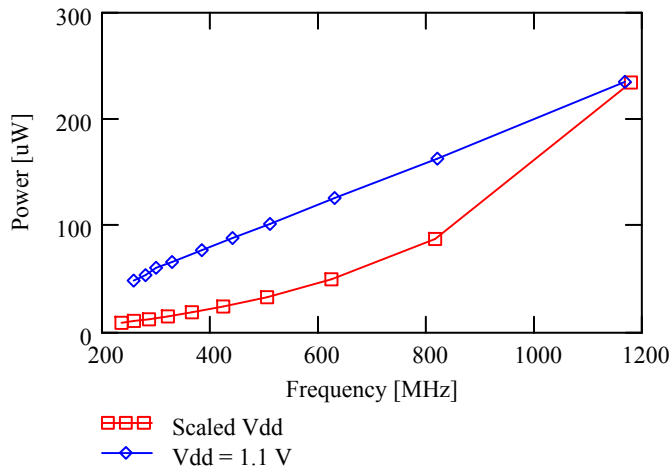
PulseWidth =	0.424	ns
	0.612	
	0.801	
	0.989	
	1.178	
	1.366	
	1.555	
	1.743	
	1.932	
	2.12	

```
VddOptData := READPRN("inverter_delay_fo4_20_vdd_opt.txt" )
```

$$I_{ave\_opt} := \overrightarrow{\left| VddOptData \langle 4 \rangle \right|} A \quad t_{p\_opt} := VddOptData \langle 7 \rangle s$$

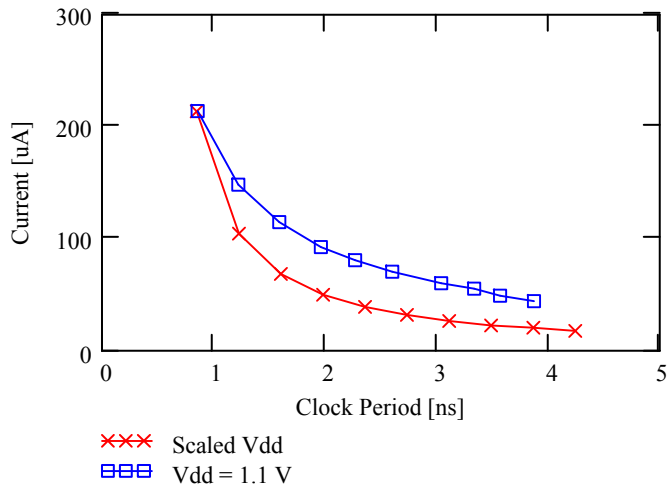
$$freq_{opt} := \frac{1}{2 \cdot t_{p\_opt}}$$

$$P_{ave\_opt} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow I_{ave\_opt_n} \cdot Vdd\_opt_n \\ x \end{array} \right.$$



We can see from the graph that reducing the supply voltage reduces the speed to the amount required.

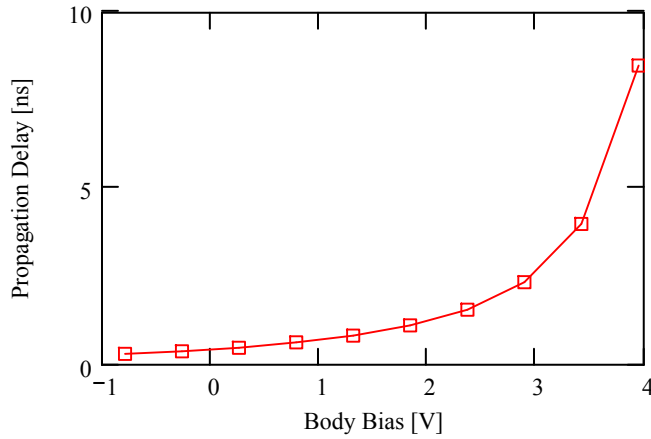
This results in a quadratic reduction in power as opposed to a linear decrease with only frequency scaling.



Part c:

BodyBiasData := READPRN("inverter\_delay\_fo4\_20\_vbb.txt")

BodyBias := BodyBiasData<sup>(0)</sup> V      BodyDelay := BodyBiasData<sup>(3)</sup> s



We can see that the inverter propagation delay decreases as the threshold voltage is increased (reverse body bias) and increases when the threshold voltage is decreased (forward body bias).

From this graph, we can determine the required body bias needed to achieve the desired propagation delay.

$$V_{\text{body\_opt}} := \begin{cases} \text{for } n \in 0..9 \\ x_n \leftarrow \text{interp}\left(\frac{\text{BodyDelay}}{s}, \frac{\text{BodyBias}}{V}, \frac{\text{PulseWidth}_n}{s}\right) \\ x \cdot V \end{cases}$$

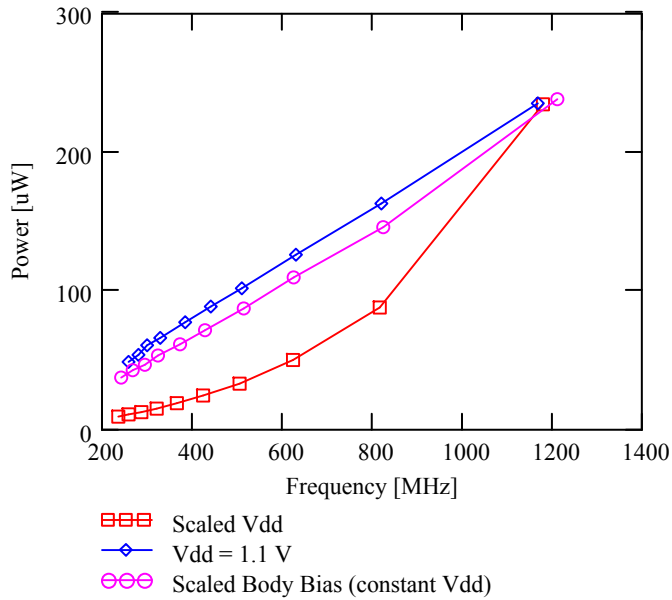
$V_{\text{body\_opt}} =$	-0.062	V
	0.699	
	1.223	
	1.596	
	1.907	
	2.132	
	2.358	
	2.488	
	2.615	
	2.741	

$\text{PulseWidth} =$	0.424	ns
	0.612	
	0.801	
	0.989	
	1.178	
	1.366	
	1.555	
	1.743	
	1.932	
	2.12	

VbbOptData := READPRN("inverter\_delay\_fo4\_20\_vbb\_opt.txt" )

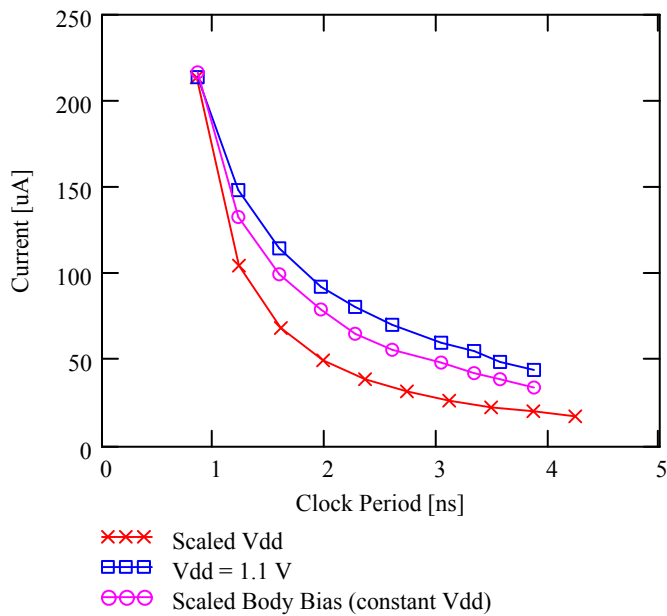
$$I_{ave\_vbb\_opt} := \overrightarrow{\left| VbbOptData \langle 4 \rangle \right|} A \quad t_{p\_vbb\_opt} := VbbOptData \langle 7 \rangle s \quad V_{dd} = 1.1 V$$

$$freq_{opt\_vbb} := \frac{1}{2 \cdot t_{p\_vbb\_opt}} \quad P_{ave\_opt\_vbb} := \left\{ \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow I_{ave\_vbb\_opt}_n \cdot V_{dd} \\ x \end{array} \right.$$



We can see from this curve that we can increase the threshold voltage by varying the substrate bias, slowing down the transistor.

The increased threshold voltage also results in decreased leakage current, thus reducing the overall power.



*Part d:*

Forward biasing the transistor bulk:

VddVbbNegData<sub>0</sub> := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg1.txt")

VddVbbNegData<sub>1</sub> := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg2.txt")

VddVbbNegData<sub>2</sub> := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg3.txt")

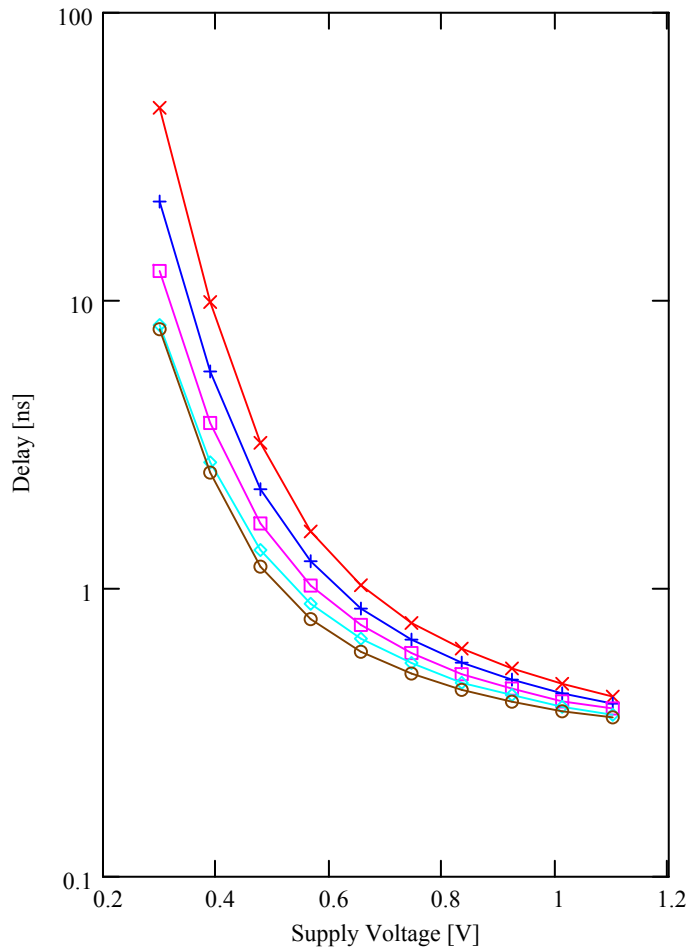
VddVbbNegData<sub>3</sub> := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg4.txt")

VddVbbNegData<sub>4</sub> := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg5.txt")

VddVbbNegData<sub>5</sub> := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg6.txt")

VddVbbNegData<sub>6</sub> := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg7.txt")

$$\text{Delay}_{\text{db\_neg}} := \begin{cases} \text{for } n \in 0..4 \\ x_n \leftarrow \left( \text{VddVbbNegData}_n \right)^{\langle 5 \rangle} \text{ s} \\ x \end{cases} \quad \text{V}_{\text{bb\_db\_neg}} := \begin{pmatrix} 0 \\ -0.15 \\ -0.3 \\ -0.45 \\ -0.6 \\ -0.75 \\ -0.9 \end{pmatrix} \text{ V}$$
$$\text{V}_{\text{dd\_db\_neg}} := \left( \text{VddVbbNegData}_0 \right)^{\langle 0 \rangle} \text{ V}$$



Note that by forward biasing the bulk of the transistors, the threshold voltage is reduced, increasing drive current and therefore speed.

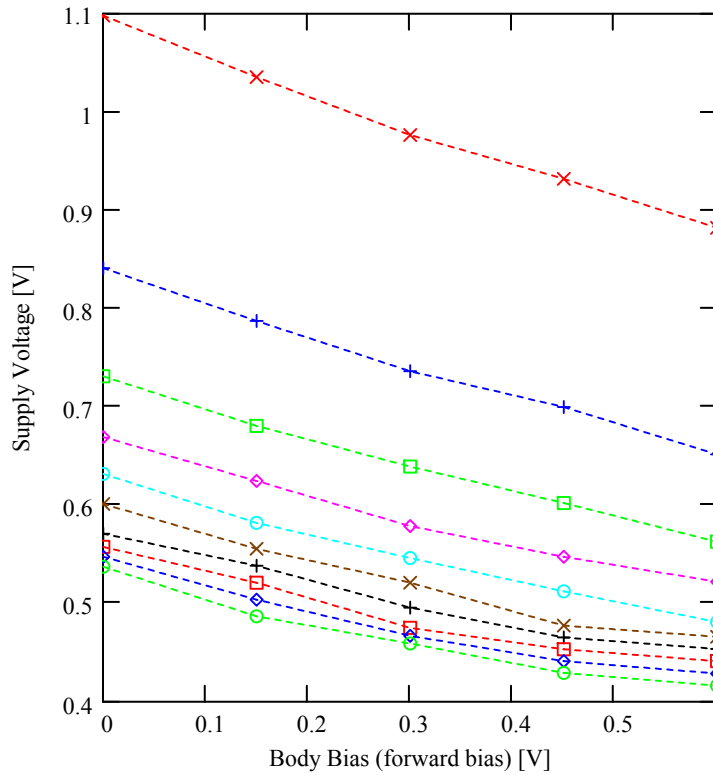
We can use this additional slack to further reduce the supply voltage, and consequently the power.

- ×××× V<sub>bb</sub> = 0 V
- + + + V<sub>bb</sub> = 0.15 V (forward bias)
- □ □ V<sub>bb</sub> = 0.30 V (forward bias)
- ◇ ◇ ◇ V<sub>bb</sub> = 0.45 V (forward bias)
- ○ ○ V<sub>bb</sub> = 0.60 V (forward bias)



Finding the corresponding Vdd and Vbb pairs for a given operating frequency:

$$V_{dd\_body\_opt}(\text{delay}) := \begin{cases} \text{for } n \in 0..4 \\ x_n \leftarrow \text{linterp}\left(\frac{-\text{Delay}_{db\_neg_n}}{s}, \frac{V_{dd\_db\_neg}}{V}, \frac{-\text{delay}}{s}\right) \\ x \cdot V \end{cases}$$



- ××× f = 278 MHz
- +++ f = 191 MHz
- f = 145 MHz
- ◇- f = 117 MHz
- f = 98 MHz
- ××× f = 85 MHz
- +++ f = 74 MHz
- f = 66 MHz
- ◇- f = 60 MHz
- f = 54 MHz

Using this data, we can then simulate the inverter chain and find the optimal Vdd-Vbb pair for each frequency point that will result in the lowest power.

$V_{dd}V_{bb}NegOptData_0 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt1.txt")$   
 $V_{dd}V_{bb}NegOptData_1 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt2.txt")$   
 $V_{dd}V_{bb}NegOptData_2 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt3.txt")$   
 $V_{dd}V_{bb}NegOptData_3 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt4.txt")$   
 $V_{dd}V_{bb}NegOptData_4 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt5.txt")$   
 $V_{dd}V_{bb}NegOptData_5 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt6.txt")$   
 $V_{dd}V_{bb}NegOptData_6 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt7.txt")$   
 $V_{dd}V_{bb}NegOptData_7 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt8.txt")$   
 $V_{dd}V_{bb}NegOptData_8 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt9.txt")$   
 $V_{dd}V_{bb}NegOptData_9 := READPRN("inverter\_delay\_fo4\_20\_vdd\_vbb\_neg\_opt10.txt")$

$$V_{supply} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow (V_{dd}V_{bb}NegOptData_n)^{\langle 1 \rangle} \\ x \cdot V \end{array} \right. \quad V_{substrate} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow (V_{dd}V_{bb}NegOptData_n)^{\langle 2 \rangle} \\ x \cdot V \end{array} \right.$$

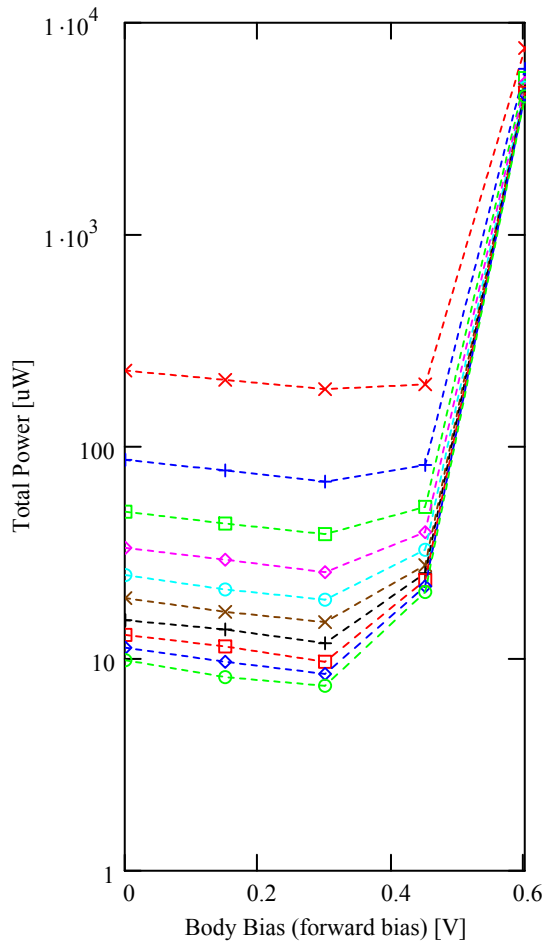
$$I_{ave\_inv20} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow \left| (V_{dd}V_{bb}NegOptData_n)^{\langle 4 \rangle} \right| \\ x \cdot A \end{array} \right. \quad t_{delay} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow \left| (V_{dd}V_{bb}NegOptData_n)^{\langle 9 \rangle} \right| \\ x \cdot s \end{array} \right.$$

$$I_{ave\_nbulk} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow \left| (V_{dd}V_{bb}NegOptData_n)^{\langle 5 \rangle} \right| \\ x \cdot A \end{array} \right. \quad I_{ave\_pbulk} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow \left| (V_{dd}V_{bb}NegOptData_n)^{\langle 6 \rangle} \right| \\ x \cdot A \end{array} \right.$$

$$P_{supply} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow (V_{supply}_n \cdot I_{ave\_inv20}_n) \\ x \end{array} \right. \quad P_{nbulk} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow (V_{substrate}_n \cdot I_{ave\_nbulk}_n) \\ x \end{array} \right.$$

$$P_{pbulk} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow \left| ((V_{supply}_n - V_{substrate}_n) \cdot I_{ave\_pbulk}_n) \right| \\ x \end{array} \right.$$

$$P_{total} := \left| \begin{array}{l} \text{for } n \in 0..9 \\ x_n \leftarrow (P_{supply}_n + P_{nbulk}_n + P_{pbulk}_n) \\ x \end{array} \right.$$



- ××× f = 278 MHz
- +++ f = 191 MHz
- f = 145 MHz
- ◇◇◇ f = 117 MHz
- f = 98 MHz
- ××× f = 85 MHz
- +++ f = 74 MHz
- f = 66 MHz
- ◇◇◇ f = 60 MHz
- f = 54 MHz

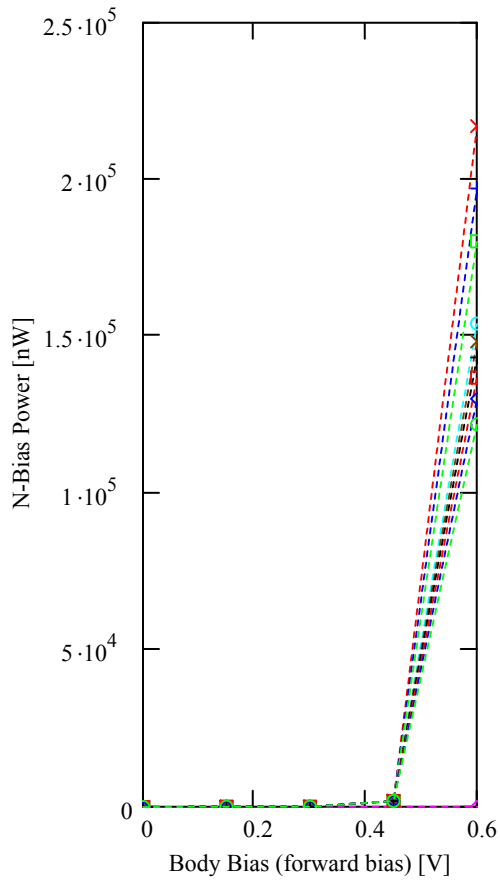
Note that as the substrate is forward biased, we can reduce the supply voltage. We expect the substrate current to increase with forward bias.

However, as seen from the plot, the power starts to increase as the S/D junction is biased in the forward active region.

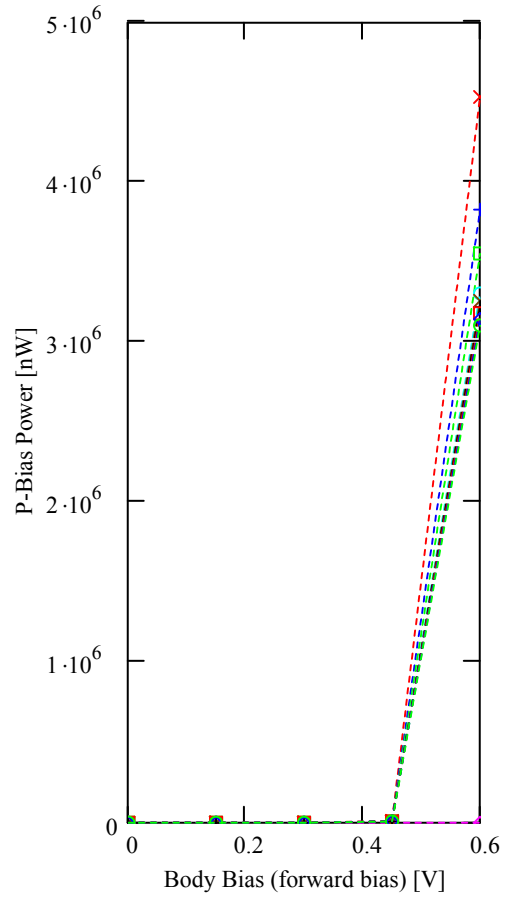
This can be attributed to the fact that the substrate current starts to dominate the overall power.

Thus we see that the minimum power occurs when the bulk is forward-biased at around 0.3 volts. This buys enough timing slack to reduce the supply voltage but still drawing a small enough current through the S/D junctions.

From these graphs, we can see the turn-on voltage of the S/D junctions:



- ××× f = 278 MHz
- +++ f = 191 MHz
- ▣▣▣ f = 145 MHz
- ◇-◇-◇ f = 117 MHz
- f = 98 MHz
- ××× f = 85 MHz
- +++ f = 74 MHz
- ▣▣▣ f = 66 MHz
- ◇-◇-◇ f = 60 MHz
- f = 54 MHz



- ××× f = 278 MHz
- +++ f = 191 MHz
- ▣▣▣ f = 145 MHz
- ◇-◇-◇ f = 117 MHz
- f = 98 MHz
- ××× f = 85 MHz
- +++ f = 74 MHz
- ▣▣▣ f = 66 MHz
- ◇-◇-◇ f = 60 MHz
- f = 54 MHz

Problem #2:

*Part a:*

The two circuit styles compared in the paper are the standard CMOS inverter circuit and the Charge Recovery (or Adiabatic) logic. The delay and energy models for each can be expressed as:

$$D_{\text{CMOS}} = \frac{C \cdot V_{\text{dd}}}{I} = \frac{C \cdot V_{\text{dd}}}{k \cdot (V_{\text{dd}} - V_{\text{th}})^2} = R_{\text{CMOS}} \cdot C \quad E_{\text{CMOS}} = \frac{1}{2} \cdot C \cdot V_{\text{dd}}^2$$
$$D_{\text{CR}} = \frac{\pi}{\omega_d} + R_{\text{CR}} \cdot C \quad E_{\text{CR}} = \frac{1}{2} \cdot C \cdot \Delta V^2 \cdot \left[ 1 - e^{\left( \frac{-\pi \alpha}{\omega_d} \right)} \right]$$
$$\alpha = \frac{R_{\text{CR}}}{2 \cdot L}$$

Since both energy expressions are dependent on the square of the supply voltage (or in the case of CR, a fraction of the supply voltage), we can use voltage scaling to quadratically reduce the energy.

*Part b:*

Without considering switching power, CMOS logic dissipates less energy until the voltage is scaled down to 1V. The point where CR starts to consume less energy has a 10X reduction in frequency and a 150X reduction in power.

With switching power considered, CMOS logic now dissipates less energy over a wider range. The voltage crossover point is reduced from 1V to voltages close to the transistor threshold voltage. Thus, with switching power considered, CR starts to consume less energy when the power is reduced 2500X at a frequency of 100X the peak.

*Part c:*

For low power designs with increased computation requirements such as portable phones, computers, PDAs, and the like, CMOS logic will be the better choice.

However, for ultra-low power, very low performance requirements, such as watches, simple sensors without much computational requirements, medical and biological implants, and the like, CR logic might be the logic style of choice.

