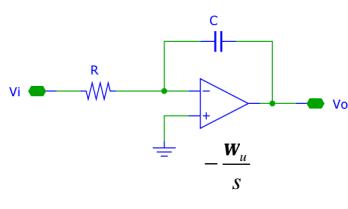


# Implementation Issues

- Component spread
- Sensitivity
- Tuning
- Noise
- Finite Gain
- Finite Bandwidth
- ...



## Finite Bandwidth



- Model finite bandwidth only

- DC gain infinite  
(keep things manageable & stand a chance to actually learn something from the calculation)

- Errors:
  - DC Gain: minor problem
  - Pole: → phase shift

- What's the effect on a filter?

$$\frac{V_o}{V_i} = -\frac{W_o}{s} \quad \underbrace{\frac{W_u}{W_o + W_u}}_{\text{DC gain error}} \quad \underbrace{\frac{1}{1 - \frac{s}{W_o + W_u}}}_{\text{pole}}$$

$$\text{with } W_o = \frac{1}{RC}$$



# Effect on Filter Response

Ideal Integrator

$$H_{\text{int\_ideal}} = -\frac{\mathbf{W}_o}{s}$$

Actual Integrator

$$H_{\text{int\_actual}} \equiv -\frac{\mathbf{W}_o}{s} \frac{1}{1 + \frac{s}{p_2}} \quad \text{with} \quad p_2 = -\mathbf{W}_u - \mathbf{W}_o \equiv -\mathbf{W}_u$$

Ideal Filter

$$H_{\text{filter\_ideal}}(s) \Big|_{s=p_{\text{ideal}}} \rightarrow \infty$$

Actual Filter

$$H_{\text{filter\_actual}} \left( s \left( 1 + \frac{s}{p_2} \right) \right) \Big|_{s=p_{\text{actual}}} \rightarrow \infty$$

$$\text{Hence : } p_{\text{ideal}} = p_{\text{actual}} \left( 1 + \frac{p_{\text{actual}}}{p_2} \right)$$

Solve for  $p_{\text{actual}}$ !



## Solving for $p_{\text{actual}}$

$$\mathbf{a}_i + j\mathbf{b}_i = \mathbf{a}_a + j\mathbf{b}_a \left( 1 + \frac{\mathbf{a}_a + j\mathbf{b}_a}{\mathbf{a}_2} \right)$$

$$p_{\text{ideal}} = \mathbf{a}_i + j\mathbf{b}_i$$

$$p_{\text{actual}} = \mathbf{a}_a + j\mathbf{b}_a$$

$$p_2 = -\mathbf{a}_2$$

$$|\mathbf{b}_i| \gg |\mathbf{a}_i| \quad (\text{high Q})$$

$$|\mathbf{b}_a| \gg |\mathbf{a}_a|$$

$$|\mathbf{a}_2| \gg |\mathbf{a}_i|, |\mathbf{a}_a|$$



$$\mathbf{a}_i \equiv \mathbf{a}_a \left( 1 + \frac{\mathbf{a}_a}{\mathbf{a}_2} \right) - \frac{\mathbf{b}_a^2}{\mathbf{a}_2}$$

$$\equiv \mathbf{a}_a - \frac{\mathbf{b}_a^2}{\mathbf{a}_2}$$

$$\mathbf{a}_a \equiv \mathbf{a}_i + \frac{\mathbf{b}_a^2}{\mathbf{a}_2} = \mathbf{a}_i \left( 1 + \frac{\mathbf{b}_a}{\mathbf{a}_i} \frac{\mathbf{b}_a}{\mathbf{a}_2} \right)$$

$$\equiv \mathbf{a}_i \left( 1 - 2Q_i \frac{\mathbf{b}_a}{\mathbf{b}_i} \frac{\mathbf{b}_a}{\mathbf{a}_2} \right) \quad \text{using} \quad \frac{\mathbf{b}}{\mathbf{a}} = -2Q$$

$$\equiv \mathbf{a}_i \left( 1 - 2Q_i \frac{\mathbf{b}_a}{\mathbf{a}_2} \right) \quad \text{assuming} \quad \mathbf{b}_a \approx \mathbf{b}_i$$

$$\equiv \mathbf{a}_i \left( 1 - 2Q_i \frac{\mathbf{W}_{\text{corner}}}{\mathbf{a}_2} \right)$$



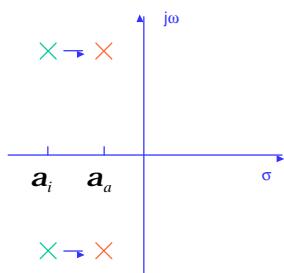
# Effect of Finite Amplifier Bandwidth

$$\mathbf{a}_a \approx \mathbf{a}_i \left( 1 - 2Q_i \frac{\mathbf{w}_{\text{corner}}}{\mathbf{a}_2} \right)$$

Example :

$$Q = 10, f_{\text{corner}} = 1\text{MHz}, f_u = 100\text{MHz}$$

$$\mathbf{a}_a \approx \mathbf{a}_i \left( 1 - 2 \times 10 \frac{1\text{ MHz}}{100\text{ MHz}} \right) = 0.8\mathbf{a}_i$$



To reduce  $\mathbf{a} < 1\%$  (and, hence increase Q by <1%) need

$$f_u > 200Qf_{\text{corner}}$$

Solution:

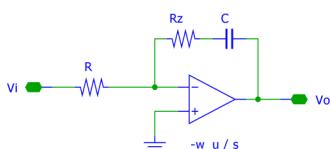
- Very fast amplifier, or
- Compensation circuit

Q enhancement → peaking in response (or instability)



# Pole-Zero Cancellation

$$\begin{aligned} H &= -\frac{1 + sR_zC}{sRC \left( 1 + \frac{s}{W_o} \right) + \frac{s}{W_u} (1 + sR_zC)} \\ &= -\underbrace{\frac{1}{sRC}}_{\text{ideal response}} \underbrace{\frac{1 + sR_zC}{1 + \frac{s}{W_u} + \frac{1}{W_u RC} (1 + sR_zC)}}_{\text{error, should be 1}} \\ &= -\frac{W_o}{s} \frac{1 + sR_zC}{1 + \frac{W_o}{W_u} + \frac{s}{W_u} \left( 1 + \frac{R_z}{R} \right)} \\ &= -\frac{W_o}{s} \frac{1}{1 + \frac{W_o}{W_u} + \frac{1 + sR_zC}{s} \frac{1 + \frac{R_z}{R}}{1 + \frac{W_o}{W_u}}} \end{aligned}$$



$$\text{Need } \frac{\left( 1 + \frac{R_z}{R} \right)}{W_u \left( 1 + \frac{W_o}{W_u} \right)} = R_z$$

$$\Rightarrow R_z \equiv \frac{1}{W_u C} \quad \text{assuming } W_u \gg W_o$$

